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On Ponderomotive Effects Induced by Alfvén Waves in Inhomogeneous 2.5D MHD Plasmas

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Abstract Where spatial gradients in the amplitude of an Alfvén wave are non-zero, a nonlinear magnetic-pressure gradient acts upon the medium (commonly referred to as the *ponderomotive force*). We investigate the nature of such a force in inhomogeneous 2.5D MHD plasmas by analysing source terms in the nonlinear wave equations for the general case of inhomogeneous \mathbf{B} and ρ , and consider supporting nonlinear numerical simulations. Our equations indicate that there are two distinct classes of ponderomotive effect induced by Alfvén waves in general 2.5D MHD, each with *both* a longitudinal and transverse manifestation. i) Geometric effects: Gradients in the pulse geometry relative to the background magnetic field cause the wave to sustain cospatial disturbances, the *longitudinal* and *transverse daughter disturbances* – where we report on the transverse disturbance for the first time. ii) $\nabla(c_A)$ effects: Where a pulse propagates through an inhomogeneous region (where the gradients in the Alfvén-speed profile c_A are non-zero), the nonlinear magnetic-pressure gradient acts to accelerate the plasma. Transverse gradients (phase mixing regions) excite independently propagating fast magnetoacoustic waves (generalising the result of Nakariakov, Roberts, and Murawski (*Solar Phys.* **175**, 93, 1997)) and longitudinal gradients (longitudinally dispersive regions) perturb along the field (thus creating static disturbances in $\beta = 0$, and slow waves in $\beta \neq 0$). We additionally demonstrate that mode conversion due the nonlinear Lorentz force is a one-way process, and does not act as a mechanism to nonlinearly generate Alfvén waves due to propagating magnetoacoustic waves. We conclude that these ponderomotive effects are induced by an Alfvén wave propagating in any MHD medium, and have the potential to have significant consequences on the dynamics of energy transport and aspects of dissipation provided the system is sufficiently nonlinear and inhomogeneous.

Keywords Magnetic fields, corona · Waves, Alfvén · Waves, magnetohydrodynamic · Waves, propagation

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1. Introduction

Due to the abundance of observational data confirming the existence and ubiquity of MHD wave motions in coronal plasma, it is clear that a well-developed theory of MHD wave propagation is required for understanding many dynamic processes ongoing in the coronal plasma (see reviews by, *e.g.*, De Moortel, 2005; Nakariakov and Verwichte, 2005; Ruderman and Erdélyi, 2009; Goossens *et al.*, 2011; De Moortel and Nakariakov, 2012). The magnetic topology of the corona supports a wide variety of features, and as such can be highly inhomogeneous. Since the behaviour of MHD waves is determined by the medium in which they propagate, an understanding of wave propagation in inhomogeneous media is essential.

One important consequence of considering propagation in an inhomogeneous medium is the concept of *phase mixing*. Simply, as a pulse or wave train propagates through the inhomogeneous medium, oscillations on neighbouring field lines become out of phase as local Alfvén speeds on each field line differ. This process naturally creates transverse gradients in the wave across the background magnetic field, and acts as a (linear) dissipative mechanism of Alfvén wave energy, and hence is often considered as a potential mechanism of coronal heating (see, *e.g.*, Heyvaerts and Priest, 1983; Browning, 1991; Narain and Ulmschneider, 1990, 1996). Typically, such studies have considered an inhomogeneity in density (to permit a unidirectional field, which makes mathematics more tractable), however, as this paper will re-enforce, the process of phase mixing is strictly dependent on a non-uniform background Alfvén speed, *i.e.* is dependent on both density and magnetic field profiles, and is not restricted to cases of density inhomogeneity only.

There is a secondary consequence of these non-zero spatial gradients in the amplitude of a propagating MHD wave: nonlinear magnetic-pressure gradients and nonlinear magnetic tension (*i.e.* the nonlinear Lorentz force) act upon the plasma. In the MHD context, these forces are often referred to as the *ponderomotive force*. Generally, a ponderomotive force is defined as a basic nonlinear force consisting of spatial gradients in a wave-field which has a non-vanishing effect when averaged over the period, however, we note that the term has been used to refer to other forces (see Allan, Poulter, and Manuel (1991) and Verwichte (1999) for discussions of the term's historical usage). The concept exists in areas of plasma physics other than MHD waves, in particular in the study of laser-plasma interaction where the force causes, including self-focusing (*e.g.* Chen, 1984) and channel formation (*e.g.* Boyd and Sanderson, 2003). The ponderomotive force in the MHD waves context (*i.e.* the nonlinear Lorentz force arising in fluid equations of motion) has been formally discussed by Dewar (1970) and Webb *et al.* (2005). For a thorough discussion of the ponderomotive force in various contexts, and a demonstration of the equivalence of particle-orbit ponderomotive force, see Allan, Poulter, and Manuel (1991), Section 3, and Appendix A.

In our case (propagating MHD waves in inhomogeneous media), the effects of such a force are primarily of interest in that they have the potential to facilitate nonlinear mode conversion, the result of which has consequences on energy transport and dissipation. In many previous studies of ponderomotive effects (*e.g.*, in almost all of the forthcoming references), because such studies are concerned with phenomena due to propagating Alfvén waves, the authors use the term ponderomotive force to refer specifically to the nonlinear magnetic pressure force (as Alfvén waves do not act on the medium via nonlinear magnetic tension, *e.g.* as shown in Section 3). However, as reported in Thurgood and McLaughlin (2012), propagating magnetoacoustic waves have a similar action on the medium, but in their case due to both nonlinear magnetic tension and nonlinear magnetic pressure. To avoid ambiguity, henceforth when referring to the force responsible for the investigated phenomena we avoid the term 'ponderomotive force' in favour of the more specific 'nonlinear magnetic-pressure

gradient' or 'nonlinear magnetic tension' as appropriate. We use the term 'ponderomotive effect' to refer to the wider family of phenomena caused by the nonlinear Lorentz force of propagating MHD waves, and in this paper we primarily consider the specific set of ponderomotive effects induced by propagating Alfvén waves. Outside of the coronal plasma context, ponderomotive effects of MHD waves have been investigated in magnetospheric physics (e.g. Rankin *et al.*, 1994; Tikhonchuck *et al.*, 1995; Allan and Manuel, 1996) and as an acceleration mechanism in the solar wind (e.g. Stark, Musielak, and Suess, 1995). Within the context of coronal plasmas, ponderomotive effects were considered initially by Hollweg (1971) and later by Nakariakov *et al.* (1997), Verwichte (1999) and Verwichte *et al.* (1999), the last three of which are key references in this paper.

Verwichte (1999) and Verwichte *et al.* (1999) considered the nonlinear evolution of an Alfvén wave in a homogeneous 1.5D model. They found that the nonlinear magnetic-pressure gradient was responsible for two features of the resultant wave behaviour. Firstly, they found that the propagating Alfvén wave sustains a disturbance which is longitudinal to the background magnetic field, and caused no net perturbation to the plasma (since the average nonlinear magnetic pressure over the wave period was zero). They dubbed this feature a *ponderomotive wing*. Secondly, they found that the interaction between two crossing Alfvén waves gives rise to a non-zero net perturbation of plasma density. Hence, in warm plasmas, this *cross-ponderomotive effect* was identified as a potential mode conversion mechanism, as would certain combinations of pulse geometry and background inhomogeneity leading to non-zero longitudinal perturbations as the pulse propagates.

Nakariakov *et al.* (1997) considered the nonlinear excitation of the fast wave by a propagating Alfvén wave which undergoes phase mixing in a unidirectional field structured by a background density profile (hence, an inhomogeneous background Alfvén speed). They derive governing wave equations, then evaluate them at an initial instant where only a pure, linear Alfvén wave is perturbing the system to find that the nonlinear fast wave equation contains a source term dependent on transverse gradients in the Alfvén wave amplitude, hence showing that nonlinear mode conversion is permitted in their scenario. This is then demonstrated in a numerical simulation, where an initial condition perturbs the medium to generate an Alfvén pulse with a profile $\propto \text{sech}^2(y)$ (where $\hat{\mathbf{B}} = \hat{\mathbf{y}}$). The pulse subsequently generates fast magnetoacoustic waves as the simulation evolves. They conclude that Alfvén waves not only heat directly via the phase mixing dissipation method as per Heyvaerts and Priest (1983) but also indirectly through nonlinear coupling to the fast wave, which is itself dissipative.

Botha *et al.* (2000) extended this work and found that the efficiency of the mode conversion is determined by the frequency and amplitude of the Alfvén wave, and by the gradient in the background Alfvén speed. Their work showed that the fast wave component eventually reached saturation, and concluded that (if the Alfvén wave amplitude is high enough) the nonlinear mode conversion can be a significant sink of Alfvén wave energy that otherwise would contribute to the linear phase mixing damping mechanisms as per Heyvaerts and Priest (1983). McLaughlin, De Moortel, and Hood (2011) further extended the work into the visco-resistive case, where they found that the equilibrium density profile (and hence the location of heating) is significantly modified by the visco-resistivity and the ponderomotive effects (*i.e.* drifting of the heating layer can occur).

In this paper, we focus on the possibility of the nonlinear Lorentz force as an agent for mode conversion in the general 2.5D MHD scenario, and also consider how ponderomotive effects identified in 1.5D models carry over. To do so, we first extend the source term analysis of Nakariakov *et al.* (1997) to a MHD scenario which may be inhomogeneous in both magnetic induction and density (*i.e.* the background Alfvén speed is inhomogeneous). Then,

we emulate the numerical experiment of Nakariakov *et al.* (1997) in light of our extended analysis to discuss previously unreported ponderomotive effects.

Thus, the paper is presented as follows: in Section 2 we derive wave equations for a general 2.5D cold plasma, to determine the set of nonlinear interactions permitted between the MHD wave modes. In Section 3, we analyse nonlinear source terms forced by general Alfvén waves, and further consider the case for harmonic Alfvén waves in Sections 3.1 and 3.2. In Section 4 we present results of the numerical experiment. Finally, we interpret our results and draw conclusions in Section 5.

2. MHD Wave Equations in a General, 2.5D $\beta = 0$ Medium

We first determine the role nonlinear terms of the MHD equations play in facilitating mode coupling in an ideal, 2.5D, $\beta = 0$ plasma permeated by a general, potential, magnetic field, which we take as $\mathbf{B}_0 = [B_x, B_y, 0]$ such that $\nabla \times \mathbf{B}_0 = \mathbf{0}$, with a background density $\rho_0 = \rho_0(x, y)$. We set $\partial/\partial z = 0$ throughout, *i.e.* take $\hat{\mathbf{z}}$ as the invariant direction. The governing, ideal, $\beta = 0$ nonlinear MHD equations are

$$\begin{aligned} \rho \left[\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} \right] &= \left(\frac{\nabla \times \mathbf{B}}{\mu} \right) \times \mathbf{B}, \\ \frac{\partial \mathbf{B}}{\partial t} &= \nabla \times (\mathbf{v} \times \mathbf{B}), \\ \frac{\partial \rho}{\partial t} &= -\nabla \cdot (\rho \mathbf{v}), \end{aligned} \tag{1}$$

where the standard MHD notation applies. Initially, the medium is flow-free ($\mathbf{v}_0 = \mathbf{0}$), and is perturbed by finite amplitude perturbations of the form $\mathbf{B} = \mathbf{B}_0 + \mathbf{b}(x, y, z, t)$, $\rho = \rho_0 + \rho_1(x, y, z, t)$, $\mathbf{v} = \mathbf{0} + \mathbf{v}_1(x, y, z, t)$. This yields

$$\begin{aligned} \frac{\partial \mathbf{v}_1}{\partial t} - \frac{1}{\mu \rho_0} (\nabla \times \mathbf{b}) \times \mathbf{B}_0 &= \frac{1}{\mu \rho_0} (\nabla \times \mathbf{b}) \times \mathbf{b} - \frac{\rho_1}{\rho_0} \frac{\partial \mathbf{v}_1}{\partial t} - \left(1 + \frac{\rho_1}{\rho_0} \right) (\mathbf{v}_1 \cdot \nabla) \mathbf{v}_1, \\ \frac{\partial \mathbf{b}}{\partial t} - \nabla \times (\mathbf{v}_1 \times \mathbf{B}_0) &= \nabla \times (\mathbf{v}_1 \times \mathbf{b}), \\ \frac{\partial \rho_1}{\partial t} + \nabla \cdot (\rho_0 \mathbf{v}_1) &= -\nabla \cdot (\rho_1 \mathbf{v}_1), \end{aligned} \tag{2}$$

where the left-hand-side/right-hand-side governs the linear/nonlinear behaviour, respectively.

We now decompose into xyz -components such that $\mathbf{v}_1 = (v_x, v_y, v_z)$ and $\mathbf{b} = (b_x, b_y, b_z)$, giving

$$\begin{aligned} \frac{\partial v_x}{\partial t} + \frac{B_y}{\mu \rho_0} \left(\frac{\partial b_y}{\partial x} - \frac{\partial b_x}{\partial y} \right) &= N_1, \\ \frac{\partial v_y}{\partial t} - \frac{B_x}{\mu \rho_0} \left(\frac{\partial b_y}{\partial x} - \frac{\partial b_x}{\partial y} \right) &= N_2, \\ \frac{\partial v_z}{\partial t} - \frac{1}{\mu \rho_0} \left(B_x \frac{\partial}{\partial x} + B_y \frac{\partial}{\partial y} \right) b_z &= N_3, \\ \frac{\partial b_x}{\partial t} - \frac{\partial}{\partial y} (v_x B_y - v_y B_x) &= N_4, \end{aligned} \tag{3}$$

$$\begin{aligned} \frac{\partial b_y}{\partial t} + \frac{\partial}{\partial x}(v_x B_y - v_y B_x) &= N_5, \\ \frac{\partial b_z}{\partial t} - \left(B_x \frac{\partial}{\partial x} + B_y \frac{\partial}{\partial y} \right) v_z &= N_6, \\ \frac{\partial \rho_1}{\partial t} + \frac{\partial}{\partial x}(\rho_0 v_x) + \frac{\partial}{\partial y}(\rho_0 v_y) &= N_7, \end{aligned}$$

where the nonlinear components N_1, \dots, N_7 are

$$\begin{aligned} N_1 &= \frac{1}{\mu\rho_0} \left[\left(b_y \frac{\partial b_x}{\partial y} \right) - \left(b_y \frac{\partial b_y}{\partial x} + b_z \frac{\partial b_z}{\partial x} \right) \right] \\ &\quad - \frac{\rho_1}{\rho_0} \frac{\partial v_x}{\partial t} - \left(1 + \frac{\rho_1}{\rho_0} \right) \left(v_x \frac{\partial}{\partial x} + v_y \frac{\partial}{\partial y} \right) v_x, \\ N_2 &= \frac{1}{\mu\rho_0} \left[\left(b_x \frac{\partial b_y}{\partial x} \right) - \left(b_x \frac{\partial b_x}{\partial y} + b_z \frac{\partial b_z}{\partial y} \right) \right] \\ &\quad - \frac{\rho_1}{\rho_0} \frac{\partial v_y}{\partial t} - \left(1 + \frac{\rho_1}{\rho_0} \right) \left(v_x \frac{\partial}{\partial x} + v_y \frac{\partial}{\partial y} \right) v_y, \\ N_3 &= \frac{1}{\mu\rho_0} \left(b_x \frac{\partial}{\partial x} + b_y \frac{\partial}{\partial y} \right) b_z \\ &\quad - \frac{\rho_1}{\rho_0} \frac{\partial v_z}{\partial t} - \left(1 + \frac{\rho_1}{\rho_0} \right) \left(v_x \frac{\partial}{\partial x} + v_y \frac{\partial}{\partial y} \right) v_z, \\ N_4 &= \frac{\partial}{\partial y}(v_x b_y - v_y b_x), \\ N_5 &= -\frac{\partial}{\partial x}(v_x b_y - v_y b_x), \\ N_6 &= \frac{\partial}{\partial x}(v_z b_x - v_x b_z) - \frac{\partial}{\partial y}(v_y b_z - v_z b_y), \\ N_7 &= -\rho_1 \left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} \right) - \left(v_x \frac{\partial}{\partial x} + v_y \frac{\partial}{\partial y} \right) \rho_1. \end{aligned}$$

Note that the nonlinear Lorentz force in the momentum equation has been considered in the alternative tension-pressure form

$$(\nabla \times \mathbf{b}) \times \mathbf{b} = (\mathbf{b} \cdot \nabla)\mathbf{b} - \frac{1}{2}\nabla(\mathbf{b} \cdot \mathbf{b})$$

so that the contributions of the different aspects may be compared. Here, $(\mathbf{b} \cdot \nabla)\mathbf{b}$ is the nonlinear magnetic tension and $\nabla(\mathbf{b} \cdot \mathbf{b})/2$ is the nonlinear magnetic-pressure gradient.

We now seek wave equations governing the evolution of the permitted wave modes. To do so, we differentiate the momentum equation terms to link the system of equations. We then find the velocity components corresponding to the fast, slow (absent in $\beta = 0$) and Alfvén wave by using the coordinate system of Thurgood and McLaughlin (2012). They use this system to not only derive governing wave equations, but to allow the formation of initial conditions that correspond to pure, distinct wave modes and to decompose propagating waves into constituent modes (we utilise this approach in our simulations in Section 3). In our 2.5D, Cartesian analysis the velocity components are thus $v_\perp = \mathbf{v}_1 \cdot (\hat{\mathbf{z}} \times \mathbf{B}_0) = -B_y v_x + B_x v_y$ (fast), v_z (Alfvén), and $v_\parallel = \mathbf{v}_1 \cdot \mathbf{B}_0 = B_x v_x + B_y v_y$ (longitudinal perturbations, where the slow mode is absent in $\beta = 0$). Hence, the governing equations are

$$\left[\frac{\partial^2}{\partial t^2} - c_A^2 \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \right] v_{\perp} = B_x \frac{\partial N_2}{\partial t} - B_y \frac{\partial N_1}{\partial t} + c_A^2 \left(\frac{\partial N_5}{\partial x} - \frac{\partial N_4}{\partial y} \right), \tag{4}$$

$$\left[\frac{\partial^2}{\partial t^2} - \frac{1}{\mu\rho_0} \left(B_x \frac{\partial}{\partial x} + B_y \frac{\partial}{\partial y} \right)^2 \right] v_z = \frac{\partial N_3}{\partial t} + \frac{1}{\mu\rho_0} \left(B_x \frac{\partial}{\partial x} + B_y \frac{\partial}{\partial y} \right) N_6, \tag{5}$$

$$\frac{\partial^2 v_{\parallel}}{\partial t^2} = B_x \frac{\partial N_1}{\partial t} + B_y \frac{\partial N_2}{\partial t}, \tag{6}$$

where $c_A = \sqrt{B_0^2/\mu\rho_0}$ is the background/equilibrium Alfvén speed that varies in the xy plane, such that $c_A = c_A(x, y)$. Note that by setting the nonlinear terms of Equations (4)–(6) to be zero (*i.e.* the right-hand-side) we revert to the linear regime, and can see that the linear, $\beta = 0$ fast waves and Alfvén waves are completely decoupled, and there are no disturbances along the magnetic field.

3. Source Term Analysis

We now consider conditions on the fluid variables that correspond to a pure, linear Alfvén wave (as per Alfvén, 1942), *i.e.* waves driven only by magnetic tension) at an early time when other modes are taken to be absent (*i.e.* coupling has not yet occurred) to determine which terms of Equations (4)–(6) will act as sources of other modes of oscillation in the general MHD case (*i.e.* terms that contribute to the acceleration of velocity components that are initially zero in the absence of the corresponding wave mode), *i.e.* we perform a source term analysis.

To do so, we take $v_z \neq 0$ and $b_z \neq 0$ with $v_x = v_y = b_x = b_y = \rho_1 = 0$ (and so $v_{\perp} = v_{\parallel} = 0$), as perturbations in the $\hat{\mathbf{z}}$ -direction correspond linearly to a pure Alfvén wave (and the linear Alfvén wave does not perturb mass density). Note that this sets $N_i = 0$ for $i = 3, \dots, 7$, and simplifies N_1 and N_2 . The wave equations (Equations (4)–(6)) become

$$\frac{\partial^2 v_{\perp}}{\partial t^2} = \frac{1}{\mu\rho_0} \frac{\partial}{\partial t} \left[b_z \left(B_y \frac{\partial}{\partial x} - B_x \frac{\partial}{\partial y} \right) b_z \right], \tag{7}$$

$$\left[\frac{\partial^2}{\partial t^2} - \frac{1}{\mu\rho_0} \left(B_x \frac{\partial}{\partial x} + B_y \frac{\partial}{\partial y} \right)^2 \right] v_z = 0, \tag{8}$$

$$\frac{\partial^2 v_{\parallel}}{\partial t^2} = -\frac{1}{\mu\rho_0} \frac{\partial}{\partial t} \left[b_z \left(B_x \frac{\partial}{\partial x} + B_y \frac{\partial}{\partial y} \right) b_z \right] \tag{9}$$

again, the right-hand-side contains the nonlinear terms.

Here, we see that there is a source term associated with v_{\perp} , thus in this case it is possible that $\partial^2 v_{\perp}/\partial t^2 \neq 0$. Inspection reveals that Equation (7) can be rewritten as:

$$\frac{\partial^2 v_{\perp}}{\partial t^2} = -\frac{1}{\mu\rho_0} \frac{\partial}{\partial t} \left[\hat{\mathbf{z}} \times \mathbf{B}_0 \cdot \nabla \left(\frac{b_z^2}{2} \right) \right]. \tag{10}$$

Hence, the Alfvén wave can cause a nonlinear magnetic-pressure gradient to arise which in turn causes the excitation of fast magnetoacoustic waves, where gradients *transverse* to \mathbf{B}_0 are responsible. Note that the term $\hat{\mathbf{z}} \times \mathbf{B}_0 \cdot \nabla$ is the gradient in the direction across field lines. This concurs with the analysis of Nakariakov *et al.* (1997), which considered nonlinear effects in a unidirectional field and found coupling terms associated with transverse gradients (note that if we specifically consider Equations (4) and (5) for such a scenario, we recover

their wave equations, see Appendix A.) Hence, the Alfvén wave exerts a transverse, nonlinear magnetic-pressure gradient in any situation in which it assumes non-zero gradients across the magnetic field. However, as highlighted by Verwichte (1999) the net perturbation will only be non-zero if the ponderomotive force averaged over a wave-period is non-zero.

Similarly, we find that the Alfvén wave can cause a nonlinear pressure gradient to arise which causes longitudinal perturbations to the equilibrium field. By rewriting Equation (9) as

$$\frac{\partial^2 v_{\parallel}}{\partial t^2} = -\frac{1}{\mu\rho_0} \frac{\partial}{\partial t} \left[\mathbf{B}_0 \cdot \nabla \left(\frac{b_z^2}{2} \right) \right] \tag{11}$$

we see that this is due to *longitudinal gradients* in the Alfvén wave amplitude, *i.e.* this is the longitudinal effect of nonlinear magnetic pressure.

We note that Equations (10) and (11) can be integrated with respect to time (see Appendix C) to yield

$$\frac{\partial v_{\perp}}{\partial t} = -\frac{\hat{\mathbf{z}} \times \mathbf{B}_0}{\mu\rho_0} \cdot \nabla \left(\frac{b_z^2}{2} \right) = -\frac{1}{\mu\rho_0} \nabla_{\perp} \left(\frac{b_z^2}{2} \right), \tag{12}$$

$$\frac{\partial v_{\parallel}}{\partial t} = -\frac{\mathbf{B}_0}{\mu\rho_0} \cdot \nabla \left(\frac{b_z^2}{2} \right) = -\frac{1}{\mu\rho_0} \nabla_{\parallel} \left(\frac{b_z^2}{2} \right), \tag{13}$$

i.e., a familiar force equation ($\mathbf{F} = m\mathbf{a}$) dependent on the square of the amplitude of the Alfvén wave field, conforming to the general definition of a ‘ponderomotive force’ discussed in Section 1. Here, we have adopted the notation $\nabla_{\perp} \equiv \hat{\mathbf{z}} \times \mathbf{B}_0 \cdot \nabla$ and $\nabla_{\parallel} \equiv \mathbf{B}_0 \cdot \nabla$ – these terms are the gradients transverse and longitudinal relative to the equilibrium magnetic field in the xy -plane.

One can also perform a source term analysis for fluid variables corresponding to an initially pure fast wave. Doing so, we find that the ponderomotive effects of the propagating fast wave do not facilitate coupling to the Alfvén mode, the fast wave does not interact with the Alfvén wave on any level, linear or nonlinear in a medium with an invariant direction (see Appendix B). Hence, we further can conclude that ponderomotive conversion in $\beta = 0$ is a one-way process from the Alfvén to the fast magnetoacoustic mode.

3.1. Harmonic Alfvén Wave

To further investigate the nature of ponderomotive coupling, we reconsider the source terms of the fast wave and longitudinal equations when forced by a harmonic linear Alfvén wave of form

$$v_z = A \cos \theta = \Re(Ae^{i\theta}), \quad \theta = \omega t - \mathbf{k} \cdot \mathbf{r}, \quad b_z = S(x, y)v_z,$$

where $S(x, y)$ is a spatial scaling term between velocity and magnetic field perturbations that is associated with the background Alfvén speed (for a linear Alfvén wave, $\mathbf{b} = \pm \sqrt{\mu\rho_0}\mathbf{v}$). If we consider that linear Alfvén waves propagate along magnetic field lines only, then the direction of the wavevector must be $\hat{\mathbf{k}} = \hat{\mathbf{B}}_0$. We also can derive a dispersion relationship from Equation (8) (linear terms only) that links frequency, wave number and Alfvén speed: $c_A^2 = \omega^2/k^2$. Thus, we can consider the wavevector to be $\mathbf{k} = k\hat{\mathbf{k}} = k\hat{\mathbf{B}}_0 = \omega\hat{\mathbf{B}}_0/c_A$, hence the function $\theta = \omega(t - \hat{\mathbf{B}}_0 \cdot \mathbf{r}/c_A)$. Inserting the harmonic form of such a wave, the source terms driving the fast and longitudinal modes (Equations (7) and (9)) become

$$\frac{\partial^2 v_{\perp}}{\partial t^2} = \frac{A^2 S^2}{\mu\rho_0} \frac{\omega^2}{c_A^2} \left[(\hat{\mathbf{B}}_0 \cdot \mathbf{r}) \nabla_{\perp}(c_A) - c_A \nabla_{\perp}(\hat{\mathbf{B}}_0 \cdot \mathbf{r}) \right] \cos 2\theta, \tag{14}$$

$$\frac{\partial^2 v_{\parallel}}{\partial t^2} = \frac{A^2 S^2 \omega^2}{\mu \rho_0 c_A^2} [(\hat{\mathbf{B}}_0 \cdot \mathbf{r}) \nabla_{\parallel}(c_A) - c_A \nabla_{\parallel}(\hat{\mathbf{B}}_0 \cdot \mathbf{r})] \cos 2\theta. \tag{15}$$

Hence, Equations (14) and (15) govern the transverse and longitudinal perturbations forced via the action of a harmonic Alfvén wave.

The forced motion is driven at double the frequency ($\cos 2\theta$) and is of order $\mathcal{O}(A^2)$, *i.e.* key features of the ponderomotive effect previously reported in the literature (see *e.g.*, Nakariakov, Roberts, and Murawski, 1997; Botha *et al.*, 2000; McLaughlin, De Moortel, and Hood, 2011). We find that perturbations to v_{\perp} and v_{\parallel} are dependent on two distinct classes of terms, one associated with gradients in the Alfvén-speed profile and the other with gradients in the geometry of the propagating pulse relative to the equilibrium magnetic field.

3.2. Instantaneous, Geometric Terms: $\nabla_{\perp}(\hat{\mathbf{B}}_0 \cdot \mathbf{r})$ and $\nabla_{\parallel}(\hat{\mathbf{B}}_0 \cdot \mathbf{r})$

It is known in 1.5D homogeneous MHD, for an Alfvén pulse propagating along a field line, that due to gradients in the wave intensity (*i.e.* ponderomotive effect) the leading flank acts to longitudinally accelerate the plasma and the rear flank acts to longitudinally decelerate the plasma, thus sustaining a *cospatial, instantaneous perturbation* that is transported along the magnetic field which, depending on the specific pulse geometry, may or may not cause a non-zero (net) longitudinal perturbation as it passes through the medium (*i.e.* the ‘ponderomotive wings’ of Verwichte, Nakariakov, and Longbottom, 1999). Regardless of whether a net perturbation to the plasma occurs, this longitudinal daughter disturbance is continually sustained by the propagating Alfvén wave and always remains *cospatial* to its progenitor (*viz.* the daughter occupies the same spatial region as the Alfvén wave). If we impose conditions equivalent to 1.5D homogeneous MHD (*i.e.* Equations (14) and (15) where $\nabla_{\perp} = 0$ and $\nabla_{\parallel}(c_A) = 0$) only one driving term remains,

$$\frac{\partial^2 v_{\parallel}}{\partial t^2} \sim \nabla_{\parallel}(\hat{\mathbf{B}}_0 \cdot \mathbf{r}),$$

i.e. this term governs the longitudinal daughter disturbance.

Our equations indicate that, if we extend our consideration to the homogeneous 2.5D case (*i.e.* allow non-zero transverse gradients), a transverse equivalent to Verwichte’s ponderomotive wings, a transverse daughter disturbance, can exist when there are transverse gradients in the pulse profile across the equilibrium magnetic field, *i.e.*:

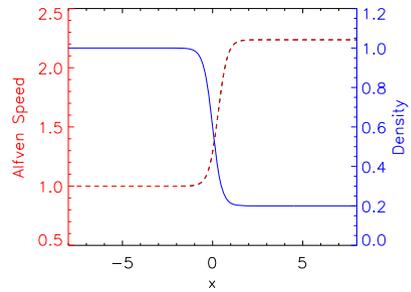
$$\frac{\partial^2 v_{\perp}}{\partial t^2} \sim \nabla_{\perp}(\hat{\mathbf{B}}_0 \cdot \mathbf{r}).$$

Such a profile, in homogeneous MHD, is imposed as an initial condition and would be maintained throughout, however, in inhomogeneous MHD a profile with transverse gradients can develop naturally via phase mixing, *i.e.* where the pulse enters a region with a transverse Alfvén-speed profile, thus assuming a pulse geometry with transverse gradients. We stress that such a transverse inhomogeneity of the Alfvén-speed profile (*i.e.* a phase mixing region) can be dependent on variable \mathbf{B}_0 and ρ_0 , and is not just upon a density inhomogeneity in a unidirectional field.

3.3. Inhomogeneity Terms: $\nabla_{\perp}(c_A)$ and $\nabla_{\parallel}(c_A)$

Now permitting $\nabla(c_A) \neq 0$ and considering 2.5D inhomogeneous MHD, our equations show the ponderomotive effects not only depend upon the instantaneous magnetic pressure perturbations of assumed pulse geometry discussed previously, but also upon magnetic pressure

Figure 1 The Alfvén-speed profile c_A (red dashed line) and the density profile ρ_0 (blue solid line). There is steep, continuous, transverse gradient in Alfvén speeds (a phase mixing region) in the region $-1 < x < 1$.



perturbations as the pulse geometry is altered from instant to instant (*i.e.* the full set of Equations (14) and (15)). This term is thus the ponderomotive effect due to Alfvén-speed profile inhomogeneities, where its transverse manifestation (which can be thought of as a phase mixing term) excites fast waves, and the longitudinal manifestation excites longitudinal perturbations (which can be thought of as a longitudinal dispersion term). If the net longitudinal perturbation is non-zero, due to the absence of gas pressure gradients in $\beta = 0$ the perturbation will be static.

Thus, the analysis of Sections 3.1–3.3 shows that the harmonic Alfvén wave nonlinearly interacts with the medium via the longitudinal and transverse manifestations of two classes of ponderomotive effect, namely the geometric effect (cospatial, ponderomotive daughter disturbances) and the $\nabla(c_A)$ effect (ponderomotive acceleration due to inhomogeneous Alfvén-speed profile). Both may yield non-zero net perturbations of the medium, causing coupling to the longitudinal and transverse (fast magnetoacoustic) modes. As the two terms may interfere (constructively or destructively), the precise dynamics of ponderomotive mode conversion will vary on a case by case basis.

4. Numerical Demonstration

We now demonstrate the ponderomotive effects identified in Sections 3–3.3 by considering simulations of a simple scenario, namely that of an initially uniform pulse separating in a unidirectional field stratified by a smooth, yet steep, transverse density profile (*i.e.* a transverse Alfvén-speed profile). Such a scenario was considered in Nakariakov *et al.* (1997), we emulate their results to demonstrate features that they did not report upon. We solve the nondimensionalised, nonlinear MHD equations using LARE2D (see Arber *et al.* (2001) for details of code and, *e.g.*, Thurgood and McLaughlin (2012) for details of the nondimensionalisation procedure, noting that all quantities are nondimensional in this section) for the equilibrium magnetic field $\mathbf{B}_0 = \hat{\mathbf{y}}$ where the plasma is structured by a density inhomogeneity of the form

$$\rho_0 = \rho_0(x) = \frac{0.2 + e^{-4x}}{1.0 + e^{-4x}}$$

in the numerical domain $x, y \in [-8, +8]$ with a resolution of 1920^2 grid points for a cold plasma initially at rest ($\mathbf{v}_0 = \mathbf{0}$).

The resulting (nondimensionalised) Alfvén-speed profile, shown in Figure 1, is thus $c_A \approx 1$ for $x < -1$, $c_A \approx \sqrt{5}$ for $x > +1$, with a steep but continuous transition between the two limits in the region $-1 < x < 1$. In this scenario (due to the unidirectional field) the longitudinal direction here is simply $\hat{\mathbf{y}}$ and the transverse direction is $\hat{\mathbf{x}}$. Thus the transverse

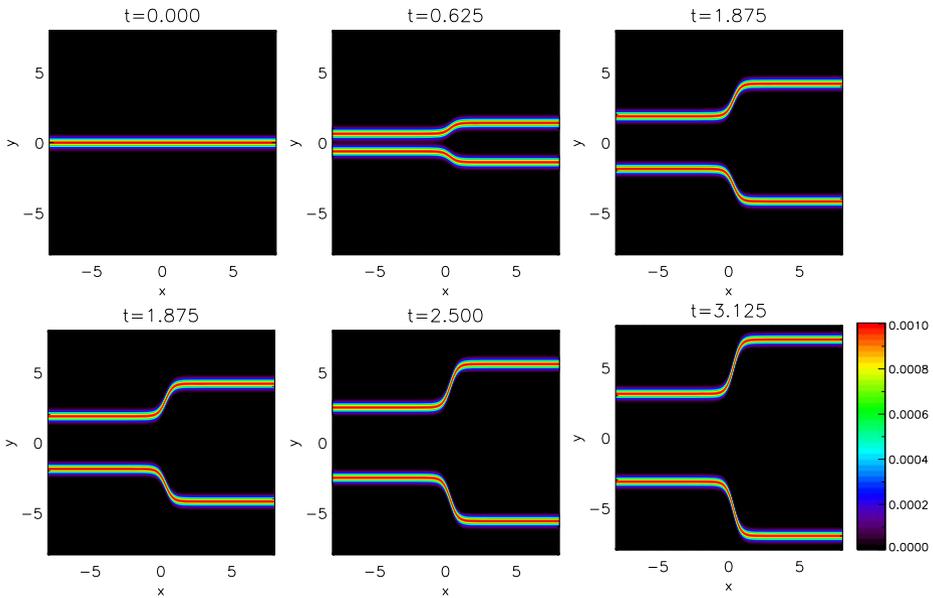


Figure 2 Contour plots of v_z , showing the propagation of the Alfvén wave, which undergoes phase mixing due to the transverse inhomogeneity in Alfvén-speed profile.

and longitudinal velocity components of the simulation (v_x and v_y) relates to the transverse and longitudinal velocity components in the previous analysis (v_\perp and v_\parallel) such that $v_\perp = -B_y v_x + B_x v_y = -v_x$ and $v_\parallel = B_x v_x + B_y v_y = v_y$.

We perturb the system by imposing an initial condition of the form

$$v_z = 2A \operatorname{sech}^2\left(\frac{y}{a}\right)$$

with pulse-width parameter $a = 0.25$, which creates an Alfvén wave (with apex at $y = 0$) which separates into two oppositely travelling pulses with amplitude $A = 0.001$. The initial amplitude is taken to be small so that if a fast wave is nonlinearly generated, it will not disturb the equilibrium field through shock wave formation. Simple reflecting boundary conditions are employed, thus the simulation is halted once the pulses reach the boundaries. Figure 2 shows the resulting separation and propagation of the Alfvén waves (seen in v_z). Throughout time, the pulse geometry maintains its initial longitudinal ($\propto \operatorname{sech}^2 y$) and transverse ($= 0$) profiles outside of the phase mixing region ($x < -1$ and $x > +1$). In the region, due to phase mixing, the profiles change in time, with the creation of transverse gradients in pulse geometry which become increasingly steep as time progresses.

We now consider perturbations to the longitudinal velocity component v_y , shown in Figure 3. Here, we note two nonlinear features. The first is a disturbance that appears to propagate as the Alfvén waves (*i.e.* along the field lines at the Alfvén speed) yet is observed in the longitudinal velocity component. These are not independently propagating waves (in our $\beta = 0$ simulation there is no gas pressure to facilitate longitudinal oscillations) but instantaneous perturbations/disturbances that are sustained and carried by the propagating Alfvén waves in v_z , *i.e.* these are the longitudinal daughter disturbances identified in Section 3.2, and is associated with longitudinal gradients in the pulse geometry (for the harmonic Alfvén wave, this was of the form $\nabla_\parallel \hat{\mathbf{B}}_0 \cdot \mathbf{r}$). The longitudinal daughter disturbance sustained by the

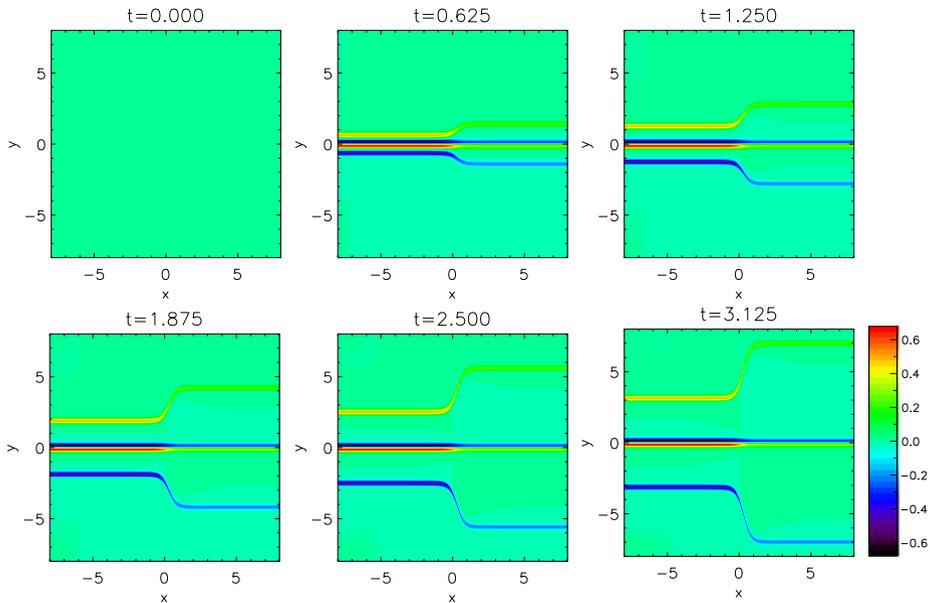


Figure 3 The longitudinal velocity component v_y for the same times as Figure 2. We find a nonlinear static perturbation localised at the initial position of the Alfvén pulse and nonlinear cospatial disturbances that are transported with the Alfvén waves. The colour bar is scaled by a factor of $\times 10^6$, *i.e.* by $\times A^2$.

upwardly propagating Alfvén wave is of the same sign, whereas the daughter sustained by the downwardly propagating wave is the opposite to its progenitor. Their maximum amplitudes are $v_y = \pm 4.999 \times 10^{-7}$, respectively, which is of $\mathcal{O}(0.5A^2)$. We note that amplitude of the longitudinal daughter is weaker by a factor of approximately $\sqrt{5}$ in the higher Alfvén speed region compared to its counterpart in the lower Alfvén speed region.

The second longitudinal ponderomotive effect is a static perturbation assuming the geometry of the initial pulse, which is also is of smaller amplitude in the higher Alfvén speed region. The fluid velocity is perturbed such that $v_y = \pm 3.031 \times 10^{-7}$ at $x = -8$ and $v_y = \pm 6.678 \times 10^{-8}$ at $x = +8$ (in the vicinity of $y = 0$), hence this perturbation is also weaker in the higher Alfvén speed region by a factor of approximately $\sqrt{5}$, *i.e.* the amplitude of the longitudinal perturbations is inversely proportional to c_A . The perturbation is accompanied by a stationary mass density enhancement (ρ_1), initially generated at the same order as the velocity perturbations (the same magnitude and with the inverse proportionality to c_A) then grows linearly in time during the simulation. These features are the 2.5D analogue of the cross-ponderomotive effect noted in the homogeneous 1.5D MHD study of Verwichte, Nakariakov, and Longbottom (1999), a non-zero longitudinal plasma perturbation caused by crossing pulses (which corresponds to our initial condition).

Figure 4 shows the transverse velocity component v_x , which is the velocity component associated with the fast magnetoacoustic wave. As reported and thoroughly detailed in Nakariakov *et al.* (1997), we find nonlinear disturbances in v_x are generated in the phase mixing region and propagate outwards from regions of high-to-low Alfvén speed, independently of the Alfvén wave, clear evidence that the Alfvén wave nonlinearly generates independently propagating fast magnetoacoustic waves as it undergoes phase mixing. As the Alfvén wave is small, the fast waves saturates at a low amplitude ($v_x = -3.338 \times 10^{-7}$)

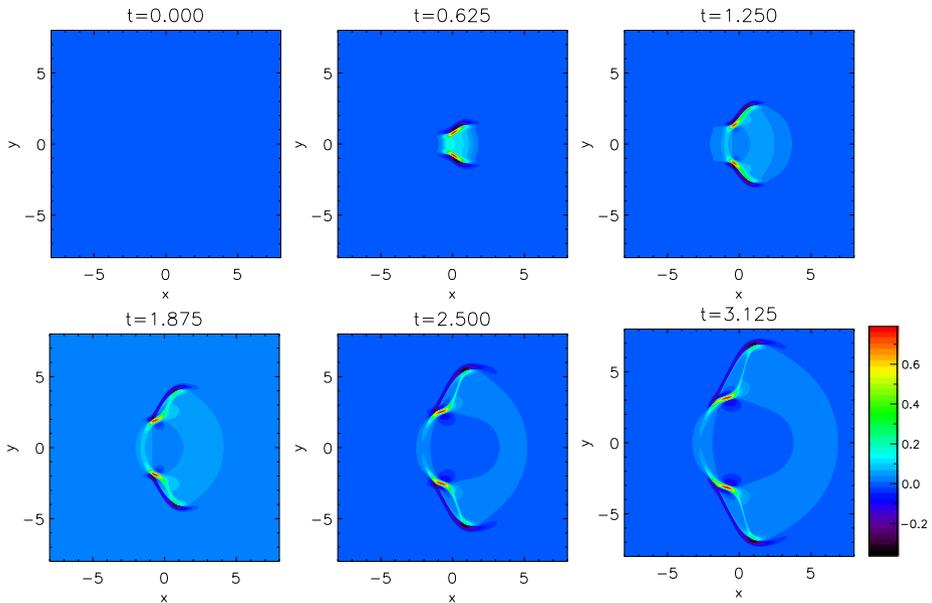


Figure 4 The transverse velocity component v_x for the same times as Figure 2. Propagating fast waves emanate from the phase mixing region. As the Alfvén wave undergoes phase mixing, independently propagating fast waves are generated and a cospatial transverse daughter disturbance develops. The colour bar is scaled by a factor of $\times 10^6$, *i.e.* by $\times A^2$.

relative to its progenitor, in agreement with Botha *et al.* (2000). Aside from outwardly propagating fast waves of Nakariakov *et al.* (1997), Figure 4 reveals that as the Alfvén wave undergoes phase mixing, a transverse cospatial disturbance arises in the region, *i.e.* we can see the *transverse daughter disturbance*. This is most clearly visible when comparing the later panels of Figure 4 to the corresponding times on Figure 2 (to determine the region cospatial to the Alfvén wave).

5. Conclusion

In this paper, we present two main results:

- The analysis and conclusions of Nakariakov *et al.* (1997) extend to the general 2.5D MHD case, such that the nonlinear magnetic pressure exerted by an Alfvén wave propagating through a region of variable Alfvén speed facilitates mode conversion from the Alfvén to magnetoacoustic modes in many MHD scenarios (to the fast mode via phase mixing and to the longitudinal mode via dispersion along field lines).
- The ponderomotive effect not only generates independently propagating magnetoacoustic waves but also longitudinal and transverse daughter disturbances, which remain cospatial and dependent upon the progenitor wave.

After deriving wave equations for a general MHD system (Equations (4)–(6)) with a non-rotational invariance (*i.e.* $\partial/\partial z = 0$), the source term analysis of Section 3 demonstrates that the nonlinear magnetic-pressure gradients generated by a propagating Alfvén wave can facilitate mode conversion from the Alfvén to magnetoacoustic modes, provided that the

pulse assumes a geometry which yields a non-zero net force over the wave's period. A similar source term analysis for a propagating fast wave is presented in Appendix B, which confirms the additional result that the process is one-way (*i.e.* the nonlinear Lorentz force does not permit conversion from the fast magnetoacoustic to the Alfvén mode). This, of course, is entirely intuitive as pressure gradients (magnetic or otherwise) cannot act in the Alfvén wave direction, as it is impossible to have gradients in an invariant direction (by definition).

In Section 3.1 we consider the terms forced by a harmonic Alfvén wave, and find that perturbations to v_{\perp} and v_{\parallel} are generated at double the frequency and at the square of the driving/initial amplitude, in agreement with results reported in the literature. Such a result is necessary for ponderomotive effects, as the nonlinear magnetic-pressure gradient acts upon the square of b_z (and hence the square of v_z). The forced wave equations (Equations (14) and (15)) are found to contain two distinct sets of terms, each with a longitudinal and transverse manifestation, which are:

- Geometric effects
 - i) $\nabla_{\parallel}(\hat{\mathbf{B}}_0 \cdot \mathbf{r})$ – Longitudinal daughter disturbances
 - ii) $\nabla_{\perp}(\hat{\mathbf{B}}_0 \cdot \mathbf{r})$ – Transverse daughter disturbances
- $\nabla(c_A)$ effects
 - iii) $\nabla_{\parallel}(c_A)$ – Perturbations due to longitudinal dispersion
 - iv) $\nabla_{\perp}(c_A)$ – Perturbations due to phase mixing

Reducing to homogeneous 1.5D MHD, we find that one term forcing longitudinal perturbations remains, corresponding to $\nabla_{\parallel}(\mathbf{B}_0 \cdot \mathbf{r})$ above, which is dependent on longitudinal gradients in a function of pulse geometry and background magnetic field. This term is responsible for the cospatial *ponderomotive wing* reported in Verwichte, Nakariakov, and Longbottom (1999). Upon permitting a transverse direction (*i.e.* homogeneous 2.5D MHD), we find that a transverse analogue is permitted. Hence, to distinguish the two we refer to the longitudinal/transverse manifestations as the *longitudinal daughter disturbance* and *transverse daughter disturbance*, respectively. When we further consider the inhomogeneous scenario and permit gradients in the Alfvén speed, a second class of forcing term is permitted, again with transverse and longitudinal manifestations, which accelerates the medium as the Alfvén wave passes through regions of inhomogeneity. The transverse manifestation occurs where the Alfvén wave undergoes phase mixing (regions with transverse gradients in Alfvén speed) and the longitudinal manifestation occurs where longitudinal dispersion occurs (in regions with longitudinal gradients in Alfvén speed), where we stress that the Alfvén-speed profiles vary with \mathbf{B}_0 and ρ_0 (*i.e.*, phase mixing can occur in regions of uniform density, if the magnetic field has transverse stratification, an example of this is magnetic null point configurations, see *e.g.*, Fruit and Craig, 2006).

To illustrate the phenomena implied by our analysis and interpretation of Sections 3–3.3, we considered numerical simulations of plasma with a unidirectional field structured by transverse density profile (the same scenario considered in Nakariakov *et al.*, 1997). In addition to the results detailed in Nakariakov *et al.* (1997) – namely, the generation of independently propagating fast waves, we find clear evidence for the existence of the longitudinal daughter disturbance, which remains cospatial to its progenitor throughout its transit. We note that the disturbance differs by a factor of $\sqrt{5}$ in the higher Alfvén speed region (relative to its amplitude in the lower Alfvén speed region). An explanation is found by re-considering Equation (15) in the limit $x = -\infty$ and $x = +\infty$ for our scenario. Specifically,

for the scenario there is no longitudinal dispersion ($\nabla_{\parallel} c_A = 0$) and both the frequency and the longitudinal geometric gradient is identical at both extremes (thus we arbitrarily take $\omega = 1$ and $\nabla_{\parallel}(\hat{\mathbf{B}}_0 \cdot \mathbf{r}) = 1$ without loss of generality), and the scaling function is taken as $S^2 = \mu\rho_0$. The equation implies

$$\max(v_{\parallel}) \approx \frac{1}{2c_A} v_z^2.$$

Given that in the simulation $c_A(x = -\infty) = 1$, $c_A(x = +\infty) = 5$ with the Alfvén wave amplitude $A = 0.001$ we find that $v_{\parallel}(x = -\infty) = 5.000 \times 10^{-7}$ and $v_{\parallel}(x = +\infty) = 2.236 \times 10^{-8}$ which is in excellent agreement with the reported amplitudes of the longitudinal daughter disturbances in the homogeneous regions. Hence, the longitudinal daughter disturbances of Alfvén waves are generated with amplitude of $\mathcal{O}(A^2/2c_A)$.

The simulations also reveal the transverse manifestation of the cospatial disturbance, the transverse daughter. This is observed to develop over time (initially, transverse gradients in pulse geometry zero) as the Alfvén wave undergoes phase mixing, remaining cospatial to the phase mixed part of the Alfvén wave. To our knowledge, this is the first time this phenomena has been reported.

An additional effect noted in the simulation is that of the static perturbation at $y = 0$ that is manifest in the longitudinal, $\hat{\mathbf{y}}$ -components of fluid variables (*e.g.* in v_y , Figure 3). We believe that this is the much the same cross-ponderomotive effect as reported in Verwichte, Nakariakov, and Longbottom (1999), despite the fact that our scenario is inhomogeneous 2.5D as opposed to the homogeneous 1.5D analysis they perform. This is because i) the cross-ponderomotive effect will not have any transverse action as Alfvén waves cannot separate in the transverse direction (and there is nothing to suggest such a phenomena in the simulation data), and ii) there is no inhomogeneity along the field lines, and hence dispersion terms ($\nabla_{\parallel} c_A$) will not, in the specific case, impact upon the separation dynamics. As our simulation is inhomogeneous (with transverse stratification), it highlights that perturbations due to the cross-ponderomotive effect are (like the other ponderomotive effects observed) inversely proportional to the speed c_A . It is, however, likely that in general, dispersion during pulse crossings will yield a more complicated effect. For cases where propagating Alfvén wave pulses are likely to meet (*e.g.* recent simulations by Matsumoto and Suzuki (2012) report wave reflection due to the transition region and, subsequently, turbulent effects in the lower solar atmosphere) and the scenario is sufficiently nonlinear it would be necessary to investigate the ponderomotive effects on interaction between Alfvén waves further. We suggest that it would be necessary integrate Equation (15) over a separation period of a general wave form on v_z (from which the form of b_z follows) that corresponds to the general solution satisfying the variable-speed 1.5D wave equation $u_{tt} = c(y)u_{yy}$ for travelling pulses from a Gaussian-like initial condition (*i.e.* a variable speed D’Alembert solution). Such an analytic solution can be found by transforming the variable speed wave equation to a constant coefficient Klein–Gordon equation, however, the profile of the wave speed has to conform to various conditions (of which, our scenario in Section 4 does not satisfy). See Grimshaw, Pelinovsky, and Pelinovsky (2010) for a comprehensive overview of the homogenisation process.

During the separation of the pulse, we also note the generation of a stationary density enhancement (initially of $\mathcal{O}(A^2/2c_A)$) that subsequently grows linearly in time. Again, this is in agreement with that reported by Verwichte, Nakariakov, and Longbottom (1999). Linear density instabilities were shown to be a general feature of $\beta = 0$ MHD by Falle and Hartquist (2002). There, the authors analyse the eigenmodes of cold MHD and show that there is a Jordan-mode instability, associated with the absent/zero-speed slow waves, which causes

such density enhancements. This instability is to shown arise when the parallel (*i.e.* slow) velocity component is not constant. The cross-ponderomotive effect of a separating Alfvén wave (or two crossing Alfvén waves), as observed in our simulations, excites such a mode by accelerating the parallel velocity component by applying a (nonlinear) magnetic pressure gradient.

Throughout the paper we have considered the cold plasma regime. If the $\beta \neq 0$ MHD wave equations (Equations (4)–(6) if gas pressure gradients are permitted) are considered under the conditions for an initially pure Alfvén wave as per Section 3, we find that gas pressure gradients do not contribute, *i.e.* the $\beta \neq 0$ equivalents of the source terms derived in Equations (7)–(15) are unchanged, *i.e.* the way in which a passing Alfvén wave nonlinearly perturbs the medium is identical to that detailed in this paper. Hence, where non-zero longitudinal perturbations of the medium occur (which are static in $\beta = 0$, *e.g.* the cross-ponderomotive perturbation in Figure 3), gas pressure gradients will subsequently arise to transport the disturbance longitudinally, *i.e.* slow magnetoacoustic waves will be generated. Thus, in $\beta = 0$, ponderomotive mode conversion is permitted between the Alfvén wave and *both* magnetoacoustic modes. In addition to the implications for mode conversion in an extension to a $\beta \neq 0$ regime, we note that the cross-ponderomotive effect, and subsequent excitation of a Jordan-mode instability, will still generate large density enhancements in low- β plasmas as per Falle and Hartquist (2002). Thus, crossing Alfvén waves will directly contribute to the creation of inhomogeneity in low- β plasmas, due to their cross-ponderomotive effects.

We note that aspects of mode conversion, coupling and interaction, explored in this paper from the perspective of applied nonlinear forces, can be investigated using alternative methods, in particular a MHD instability approach. The relationship between the results presented here, and literature on Alfvén wave instabilities (such as, *e.g.*, Derby, 1978; Goldstein, 1978; Champeaux, Passot, and Sulem, 1997; Webb *et al.*, 2001) will be explored in future work.

We conclude the paper by highlighting that all of the analysis can be repeated with different types of invariant coordinate system. For instance, we could consider azimuthal invariance, or the general coordinate system of Thurgood and McLaughlin (2012) for zero-helicity topologies, and yield the same results. Given that an invariant coordinate is a necessary condition for the existence of true Alfvén waves as per Alfvén (1942) (see, *e.g.*, Parker, 1991 and Section 2.3.1 of Thurgood and McLaughlin, 2012), we believe our results and conclusions extend to any scenario in which an Alfvén wave (a wave driven by magnetic tension only) can exist. We have shown that a nonlinear Lorentz force of a propagating Alfvén wave can generate independently propagating fast and slow magnetoacoustic waves, dependent on the interplay between Alfvén speed profile and pulse geometry (*viz.*, the form of the daughter disturbances), which varies on a case by case basis. As the transient properties of the magnetoacoustic modes are fundamentally different to the Alfvén wave, such conversion facilitates the indirect transport and dissipation of (initially) Alfvén wave energy to plasma regions that are inaccessible in the linear MHD regime. In modelling wave behaviour in sufficiently nonlinear solar plasmas, the ponderomotive effects of propagating waves must be evaluated.

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Appendix A: Recovery of Wave Equations for a Medium with a Homogeneous Magnetic Field and a Transverse Density Profile (Nakariakov, Roberts, and Murawski, 1997)

Here we demonstrate that our general wave equations for 2.5D MHD (Equations (4) and (5)) reduce to those considered in the case of Nakariakov *et al.* (1997), which considered a unidirectional homogeneous magnetic field structured by a transverse density profile. To do so, we take the field as constant in \hat{y} , *i.e.* $\mathbf{B}_0 = B_0\hat{y}$, $B_x = 0$, and $B_y = B_0$ and consider density as a function transverse to the field, *i.e.* $\rho_0 = \rho_0(x)$. Thus, the Alfvén and fast wave equations (Equations (4) and (5)) become

$$\left[\frac{\partial^2}{\partial t^2} - c_A^2(x) \frac{\partial^2}{\partial y^2} \right] v_z = \frac{\partial N_3}{\partial t} + \frac{B_0}{\mu\rho_0(x)} \frac{\partial N_6}{\partial y}, \tag{16}$$

$$\left[\frac{\partial^2}{\partial t^2} - c_A^2 \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \right] v_\perp = -B_0 \frac{\partial N_1}{\partial t} - c_A^2(x) \frac{\partial N_4}{\partial y} + c_A^2(x) \frac{\partial N_5}{\partial x}. \tag{17}$$

The Alfvén wave equation (Equation (16)) is only superficially different from the equation governing the Alfvén wave in Nakariakov *et al.* (1997), which (in their notation) is

$$\left[\frac{\partial^2}{\partial t^2} - c_A^2(x) \frac{\partial^2}{\partial z^2} \right] v_y = \frac{1}{\rho_0(x)} \left(\frac{\partial N_2}{\partial t} + \frac{B_0}{4\pi} \frac{\partial N_5}{\partial z} \right), \tag{18}$$

where the apparent difference is due to the following.

- The analysis of Nakariakov *et al.* (1997) considered \hat{y} as the invariant direction, hence v_y corresponds to the Alfvén wave (as opposed to v_z in this paper as \hat{z} is invariant). Additionally, $\partial/\partial y$ corresponds to $\partial/\partial z$ in this paper and Nakariakov *et al.* (1997), respectively.
- Hence, the nonlinear terms have a different ordering; their $N_1, N_2, N_3, N_4, N_5, N_6, N_7$ corresponds to our $N_1, N_3, N_2, N_4, N_6, N_5, N_7$, respectively.
- The nonlinear terms originating in the equation of motion (N_1, N_2, N_3) are not exactly identical. They differ by a factor of ρ_0^{-1} (we divided through the equation of motion by ρ_0 to group it with the nonlinear terms, they left it with the linear terms, *e.g.*, our N_1 is equal to their N_1/ρ_0).
- Nakariakov *et al.* (1997) use cgs units, as opposed to SI in this paper.

The fast wave equation of Nakariakov *et al.* (1997) is

$$\left[\frac{\partial^2}{\partial t^2} - c_A^2(x) \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \right] v_x = \frac{1}{\rho_0(x)} \left(\frac{\partial N_1}{\partial t} + \frac{B_0}{4\pi} \frac{\partial N_4}{\partial z} - \frac{B_0}{4\pi} \frac{\partial N_6}{\partial x} \right). \tag{19}$$

The above only differs from our fast wave equation as per the aforementioned superficial differences. Additionally, the nonlinear terms (right hand side) differ by a factor of $-B_0$. The explanation is simple – in this case $v_\perp = \mathbf{v}_1 \cdot \hat{z} \times \mathbf{B}_0 = -B_0 v_x$. Both correspond to a transverse perturbation of the field in this scenario and hence wave equations on either describe the evolution of the Alfvén wave; in a homogeneous field it is simpler to use v_x , for an inhomogeneous field v_\perp is required. Expressing v_\perp in terms of v_x and simplifying reduces our fast wave equation (Equation (17)) to the comparable form

$$\left[\frac{\partial^2}{\partial t^2} - c_A^2(x) \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \right] v_x = \frac{\partial N_1}{\partial t} + \frac{B_0}{\mu\rho_0(x)} \frac{\partial N_4}{\partial y} - \frac{B_0}{\mu\rho_0(x)} \frac{\partial N_5}{\partial x}. \tag{20}$$

Appendix B: Nonlinear Effects of a Propagating Fast Wave

We can set $v_z = 0$ and $b_z = 0$ and place restrictions on $v_x, v_y, b_x,$ and b_y that correspond to $v_{||} = b_{||} = 0, v_{\perp} \neq 0, b_{\perp} \neq 0$ and $\rho_1 \neq 0$ to consider the ponderomotive effects caused by a fast wave, yielding

$$\left[\frac{\partial^2}{\partial t^2} - c_A^2 \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \right] v_{\perp} = B_x \frac{\partial N_2}{\partial t} - B_y \frac{\partial N_1}{\partial t} + c_A^2 \left(\frac{\partial N_5}{\partial x} - \frac{\partial N_4}{\partial y} \right) \neq 0, \tag{21}$$

$$\frac{\partial^2 v_z}{\partial t^2} = 0, \tag{22}$$

$$\begin{aligned} \frac{\partial^2 v_{||}}{\partial t^2} &= \frac{1}{\mu \rho_0} \frac{\partial}{\partial t} \left\{ B_x b_y \left[\left(\frac{\partial b_x}{\partial y} \right)_T - \left(\frac{\partial b_y}{\partial x} \right)_P \right] + B_y b_x \left[\left(\frac{\partial b_y}{\partial x} \right)_T - \left(\frac{\partial b_x}{\partial y} \right)_P \right] \right\} \\ &= \frac{1}{\mu \rho_0} \frac{\partial}{\partial t} \left[b_{\perp} \left(\frac{\partial b_x}{\partial y} - \frac{\partial b_y}{\partial x} \right) \right], \end{aligned} \tag{23}$$

where subscripts T and P indicate whether a term is contributed by magnetic tension or magnetic pressure, respectively, and $b_{\perp} = \mathbf{b} \cdot \hat{\mathbf{z}} \times \mathbf{B}_0$ is the transverse perturbation of the magnetic field. The key result here is that Equation (22) shows that the fast wave does not interact with the Alfvén wave on any level; linear or nonlinear.

However, Equation (23) contains source terms, thus a propagating fast wave does cause nonlinear field-aligned disturbances that will cause, in certain circumstances, nonlinear Lorentz force coupling (via both nonlinear magnetic pressure/ponderomotive force and nonlinear magnetic tension. Departing from the $\beta = 0$ case, these source terms remain, *i.e.* the magnetoacoustic modes are coupled linearly by gas-pressure gradients, and nonlinearly by the Lorentz force.

Equation (21) shows that such an initial fast wave undergoes self-interaction. In this case, this is due to a combination of nonlinear Lorentz force, convective acceleration (contained within N_1 and N_2 which are permitted to be non-zero) and nonlinear induction (N_4 and N_5). Interestingly, the nonlinear induction term can be rewritten as

$$c_A^2 \left(\frac{\partial N_5}{\partial x} - \frac{\partial N_4}{\partial y} \right) = -c_A^2 \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \mathbf{v} \cdot \hat{\mathbf{z}} \times \mathbf{b},$$

i.e. the nonlinear induction term is effectively of the same form as that of the linear motion due to velocity perturbations across the equilibrium field, however, is instead motion due to perturbations across the induced magnetic field (though at the equilibrium, not induced, Alfvén speed).

Finally, we note that although there are no slow waves in the $\beta = 0$ case, the nonlinear source term due to the Lorentz force acting upon the Alfvén wave (the right hand side of Equation (22)) would remain unchanged for $\beta \neq 0$. This source term remains zero if an Alfvén wave is initially absent. Thus, the nonlinear Lorentz force does not facilitate slow to Alfvén mode conversion either. Hence, the analysis shows that for any 2.5D MHD scenario that there is a one-way, nonlinear mode conversion mechanism between the Alfvén and (both) magnetoacoustic modes that will become manifest when a phase mixed/ dispersive Alfvén wave (via propagating in the vicinity of an inhomogeneous Alfvén-speed profile) assumes a geometry that exerts a non-zero average force over its period perturbing along and across the magnetic field.

Appendix C: Derivation of Force Equations (Equations (12) and (13))

We demonstrate that Equations (10) and (11) can be integrated with respect to time to yield the force equations (Equations (12) and (13)) (*i.e.*, with zero value ‘integration constants’) by simply considering an alternate, direct derivation from the momentum equation.

Under the source-term conditions of Section 3 ($v_z \neq 0$ and $b_z \neq 0$ with $v_x = v_y = b_x = b_y = \rho_1 = 0$) the \hat{x} and \hat{y} components of the momentum equation simplify to yield

$$\frac{\partial v_x}{\partial t} = -\frac{1}{\mu\rho_0} b_z \frac{\partial b_z}{\partial x} = -\frac{1}{2\mu\rho_0} \frac{\partial b_z^2}{\partial x},$$

$$\frac{\partial v_y}{\partial t} = -\frac{1}{\mu\rho_0} b_z \frac{\partial b_z}{\partial y} = -\frac{1}{2\mu\rho_0} \frac{\partial b_z^2}{\partial y}.$$

From which Equations (12) and (13) readily follow by constructing equations in terms of v_{\perp} and v_{\parallel} from $v_{\perp} = \mathbf{v}_1 \cdot (\hat{\mathbf{z}} \times \mathbf{B}_0) = -B_y v_x + B_x v_y$ and $v_{\parallel} = \mathbf{v}_1 \cdot \mathbf{B}_0 = B_x v_x + B_y v_y$.

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