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Strong tidal variations in ice flow observed across the entire Ronne Ice Shelf and adjoining ice streams

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Abstract. We present a compilation of GPS time series, including those for previously unpublished sites, showing that flow across the entire Ronne Ice Shelf and its adjoining ice streams is strongly affected by ocean tides. Previous observations have shown strong horizontal diurnal and semidiurnal motion of the ice shelf, and surface flow speeds of Rutford Ice Stream (RIS) are known to vary with a fortnightly (M_{sf}) periodicity. Our new data set shows that the M_{sf} flow modulation, first observed on RIS, is also found on Evans, Talutis, Institute, and Foundation ice streams, i.e. on all ice streams for which data are available. The amplitude of the M_{sf} signal increases downstream of grounding lines, reaching up to 20 % of mean flow speeds where ice streams feed into the main ice shelf. Upstream of ice stream grounding lines, decay length scales are relatively uniform for all ice streams but the speed at which the M_{sf} signal propagates upstream shows more variation. Observations and modelling of tidal variations in ice flow can help constrain crucial parameters that determine the rate and extent of potential ice mass loss from Antarctica. Given that the M_{sf} modulation in ice flow is readily observed across the entire region at distances of up to 80 km upstream of grounding lines, but is not completely reproduced in any existing numerical model, this new data set suggests a pressing need to identify the missing processes responsible for its generation and propagation. The new GPS data set is publicly available through the UK Polar Data Centre at <http://doi.org/10.5285/4fe11286-0e53-4a03-854c-a79a44d1e356>.

1 Introduction

Ocean tides affect the flow of ice shelves (Doake et al., 2002; Legresy et al., 2004; Brunt et al., 2010; King et al., 2011a; Makinson et al., 2012) and ice streams (Anandakrishnan and Alley, 1997; Bindschadler et al., 2003b, a; Anandakrishnan et al., 2003; Gudmundsson, 2006; Marsh et al., 2013), often far upstream of their grounding lines (GLs). The growing availability of high temporal resolution data, particularly using GPS, has made the extent of these tidal effects increasingly apparent.

The Weddell Sea region is an ideal place to look for tidal effects on ice flow as it is subjected to the largest tides in Antarctica, with a tidal range of ~ 7 m at the GLs of ice streams along the Zumberge Coast (Padman et al., 2002). The semidiurnal M_2 (principal lunar) and S_2 (principal solar)

tides dominate the vertical tidal signal beneath most of the ice shelf and are characterized by an amphidromic point at the Ronne Ice Shelf calving front (Fig. 1a; Padman et al., 2002). An amphidromic point (or tidal node) is a point at which a tidal constituent has zero amplitude, around which that constituent rotates. The diurnal tides are smaller in amplitude, with no amphidromes in the region of interest and the phase propagating from east to west (Fig. 1b). These large and spatially variable tides have been observed to cause large temporal variations in the ice flow of this region, which in turn provides a unique opportunity to gain insights into ice-flow processes.

On the Whillans Ice Stream in the Ross Sea region, observations of stick-slip behaviour, modulated by the ocean tides (Bindschadler et al., 2003b, a), have proved invaluable

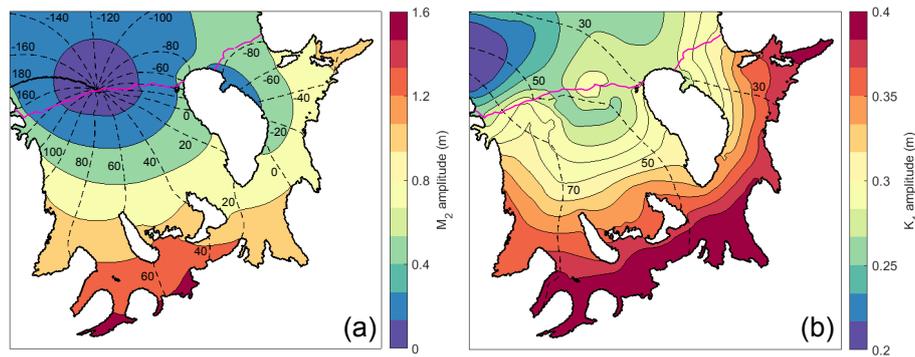


Figure 1. Amplitudes of the vertical semidiurnal M_2 (a) and diurnal K_1 (b) tides in the Weddell Sea region. Dashed lines are 20° phase lines (also labelled in degrees), with the M_2 amphidromic point visible as the minimum in amplitude in (a). Solid magenta line shows the seaward extent of the FRIS. Note the difference in colour scale between the two panels. Amplitudes and phases are taken from the circum-Antarctic inverse model (CATS2008a, which is an updated version of the inverse tide model described by Padman et al., 2002).

to our understanding of the dynamics of its flow (Winberry et al., 2011, 2009; Sergienko et al., 2009; Winberry et al., 2014; Walker et al., 2016). Nearby, the flow of Bindschadler Ice Stream responds differently, exhibiting smooth diurnal velocity fluctuations in response to the mainly diurnal vertical tides (Anandkrishnan et al., 2003). On the Filchner–Ronne Ice Shelf (FRIS) semidiurnal tidal motions have been observed to reach up to $\pm 300\%$ of the mean flow (Makinson et al., 2012) and modulation of the flow of Ross Ice Shelf front is almost as large (Brunt et al., 2010). Attempts to produce models that can replicate these observations on ice shelves have had mixed results (Makinson et al., 2012; Brunt and MacAyeal, 2014).

A very different type of behaviour has been observed on Rutford Ice Stream (RIS), with fortnightly (2-weekly, M_{sf}) variations in horizontal ice velocity of up to 20% of the mean flow (Gudmundsson, 2006). This observation is doubly interesting, in that it travels far upstream from the GL and the fortnightly period of the response is largely absent in the vertical tide that forces it. It also poses a potential aliasing issue when interpreting InSAR velocities based on image pairs separated by only a few days (Gudmundsson, 2006). Observations of fortnightly variations in ice flow have, until now, been limited to the Rutford Ice Stream (Gudmundsson, 2006), Larsen C Ice Shelf (King et al., 2011a) and Brunt Ice Shelf (G. H. Gudmundsson et al., 2017). Given the large semidiurnal tides across most of the Weddell Sea region it has been suggested that all large ice streams in this region will exhibit a behaviour similar to the RIS (Gudmundsson, 2007).

A number of mechanisms have been proposed to generate the nonlinearity which leads to this fortnightly signal, including a nonlinear basal sliding law (Gudmundsson, 2007, 2011; Rosier et al., 2014b), subglacial hydrology (Thompson et al., 2014; Rosier et al., 2015), asymmetric GL migration (Rosier et al., 2014b; Robel et al., 2017), and margin widening (Minchew et al., 2016). All of these mechanisms

can generate an M_{sf} modulation in ice flow and may have validity for certain regions. However, a unified model is yet to reproduce all aspects of the observed behaviour. This has been highlighted by various recent observations, including the presence of an M_{sf} signal on ice shelves that are not fed by large ice streams (King et al., 2011a; G. H. Gudmundsson et al., 2017), and amplification of the RIS signal downstream of the GL (Minchew et al., 2016)

Here, we present a compilation of GPS data, including previously unpublished data on Evans (EIS), Talutis (TIS), and Foundation (FIS) ice streams and Carlson Inlet. In total, we include data from 28 new GPS sites, in addition to a new analysis of 15 previously published sites, and demonstrate for the first time the pervasive nature of these nonlinear tidal effects, easily observable across the entire region both on the ice shelf and upstream of ice stream GLs.

2 Observations and data analysis

A systematic campaign of GPS receiver deployments, designed to look for tidal modulation in ice flow, has been ongoing across the FRIS for a number of years. Some data have been published both for the main body of the floating ice shelf and the Rutford Ice Stream, but not for the remaining ice streams feeding into the ice shelf. The locations of all GPS receivers included in this compilation are shown in Fig. 2 and Table A1 summarizes key information for each site. GPS stations were powered with batteries charged by solar panels, and in some cases wind turbines to allow for continuous data collection over the winter.

All tidal constituents discussed in the text are listed in Table 1 with their respective periods. For an approximate indication of their relative importance in the vertical tides of this region we include a normalized amplitude, taken from the site FR05 time series, which is approximately central to the GPS sites presented here. This shows that, in terms of the vertical tides, the principal semidiurnal and diurnal constituents

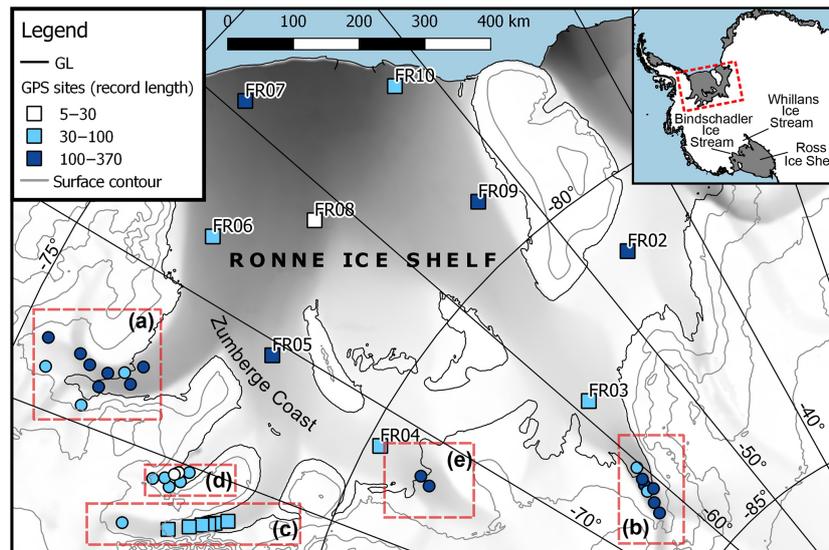


Figure 2. Map of the Filchner–Ronne Ice Shelf and adjoining ice streams. Circular markers show the location of new GPS sites included in this study and square markers are previously published sites. Marker colour indicates the approximate record length in days. The background colour scale shows ice speed from 0 to 2000 m a^{-1} (white to black); grey lines are ice surface contours at 400 m intervals and black lines are grounding lines. Dashed red boxes mark the extent of panels for Evans Ice Stream (a), Foundation Ice Stream (b), Rutford Ice Stream (c), Talutis Ice Stream and Carlson Inlet (d), and Institute Ice Stream (e), which are also shown in Fig 3. Ice speed is from the MEaSUREs data set (Rignot et al., 2011), smoothed with a 1 km low-pass boxcar filter.

Table 1. Tidal constituents discussed in the text with their respective periods in days. Normalized amplitude is the vertical amplitude of each constituent at site FR05 as measured by GPS, normalized by the largest constituent (M_2). Constituents marked with “–” were not considered significant by the tidal analysis and so their amplitudes are not shown.

Constituent name	Period (days)	Normalized vertical amplitude (m)
M_2	0.5175	1.000
S_2	0.5000	0.645
O_1	1.0758	0.397
K_1	0.9973	0.395
M_f	13.6608	0.037
S_{sa}	182.6282	0.029
M_{sf}	14.7653	–

are most important whereas long-period constituents, most notably the M_{sf} , are almost completely absent. Although the vertical tide has a spring–neap cycle which has the same fortnightly periodicity as the M_{sf} , this is a wave envelope resulting from superposition of the two semidiurnal constituents and so does not contain any tidal energy at the M_{sf} frequency (strictly speaking there is a weak astronomical forcing at the M_{sf} frequency but it is not statistically significant in our vertical GPS data).

For the results and discussion that follow we will typically refer to ice displacements, rather than velocities. The main

reason for this is that displacements are the direct result of GPS measurements, whereas velocities require taking derivatives of these observations potentially leading to noisy results (due to data errors) that require careful filtering.

GPS observations were made at a total of 43 sites using dual frequency GPS receivers placed on the ice surface. Processing of the nine previously published FR sites (all sites whose names begin with FR) was not redone and is described by King et al. (2011b) and King (2011). For all remaining sites the GPS data were processed using the kinematic precise-point positioning capabilities of the Bernese GNSS processing software, as described by Dach et al. (2009).

Our Bernese PPP analysis sub-samples the raw data to 30 s intervals and produces a three-dimensional position time series, with a correction for the solid earth tides. For the FR sites, additional corrections were made for the inverse barometer effect and ocean tide loading, as described by King et al. (2011b) and King (2011). For all other sites these corrections were not done since, in terms of the horizontal tidal motion to which we restrict our analysis, their effects are negligible. The processed results were subsequently down-sampled using cubic interpolation and the X and Y positions then analysed to 5 min intervals. The number of useful days for each site, as shown in Table A1, is defined here as days with at least 95 % data coverage.

Tidal analysis was done for every site using the “Unified Tidal analysis and prediction” MATLAB[®] software, referred to henceforth as UTide (Codiga, 2011). UTide uses an iteratively reweighted least squares (IRLS) solution method

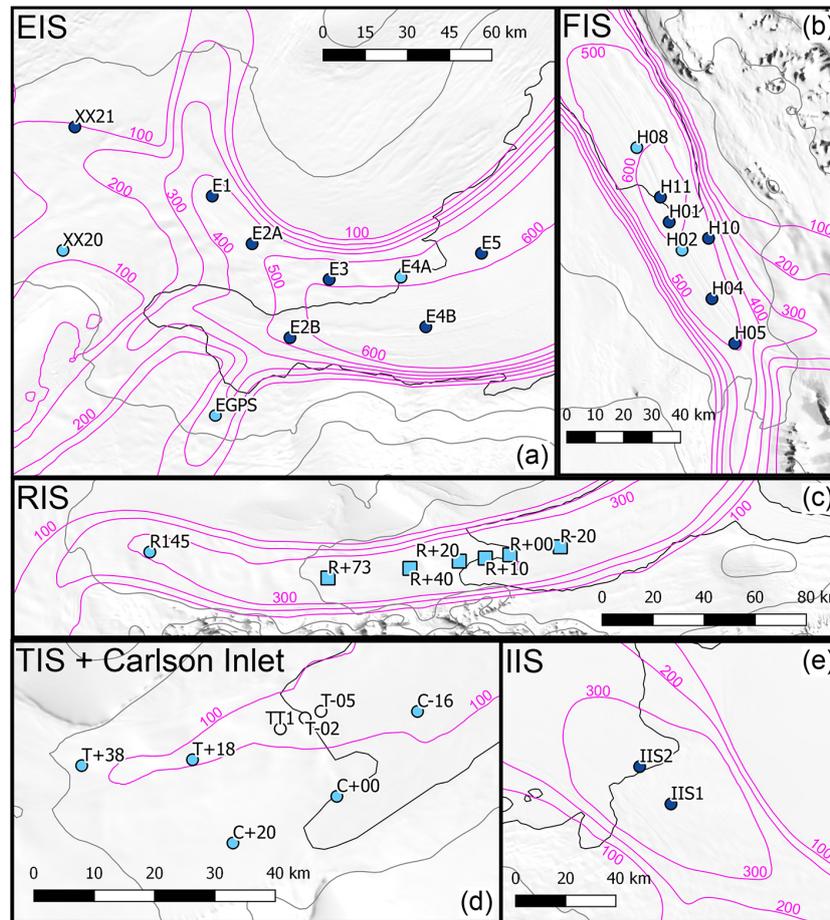


Figure 3. Close-up maps for each ice stream with relevant GPS data, including Evans Ice Stream (EIS, **a**), Foundation Ice Stream (FIS, **b**), Rutford Ice Stream (RIS, **c**), Talutis Ice Stream (TIS, **d**), and Institute Ice Stream (IIS, **e**). Magenta lines are velocity contours at 100 m a^{-1} intervals, black lines are grounding lines, and grey lines are ice surface contours at 400 m intervals. Background shading is MOA satellite imagery (Haran et al., 2014). Scale bars are shown separately for each map.

in which each observation is weighted to minimize the influence of outliers. Remaining residuals in the tidal fit may include low-frequency and/or weather effects in addition to the noise resulting from measurement error. UTide makes use of the spectral properties of these underlying residuals and Monte Carlo uncertainty propagation to determine confidence intervals for the ellipse parameters (which are non-linear functions of the least squares model parameters). The Rayleigh criterion (Pugh, 1996) was used by UTide to select which constituents were to be included in the analysis.

Each GPS record consists of three-dimensional positions, but we limit our discussion to the horizontal components of ice flow. We interpret the horizontal motion in terms of a tidal ellipse, which can be thought of as two polar vectors rotating in opposite directions such that when the vectors are aligned the speed is maximized and minimized when they oppose one another. If the two polar vectors have amplitudes a^+ and a^- and phases ϵ^+ and ϵ^- then the tidal ellipse can

be conveniently characterized by four parameters:

$$L_q^{\text{smaj}} = a_q^+ + a_q^-, \quad (1)$$

$$L_q^{\text{smin}} = a_q^+ - a_q^-, \quad (2)$$

$$\theta_q = \text{mod} \left[\frac{\epsilon_q^+ + \epsilon_q^-}{2}, \pi \right], \quad (3)$$

and

$$\varphi_q = -\epsilon_q^+ + \theta_q, \quad (4)$$

where L^{smaj} , L^{smin} , θ , and φ are the semi-major and semi-minor axis lengths, inclination, and Greenwich phase lag of the velocity vector respectively, and q is the subscript for each constituent (Pugh, 1996). Figure 4 shows the ellipse parameters diagrammatically. For the sake of brevity, wherever we discuss the amplitude of tidal constituents in GPS displacement data, we mean specifically the length of the semi-major axis. In the case of the M_{sf} signal, which is the focus

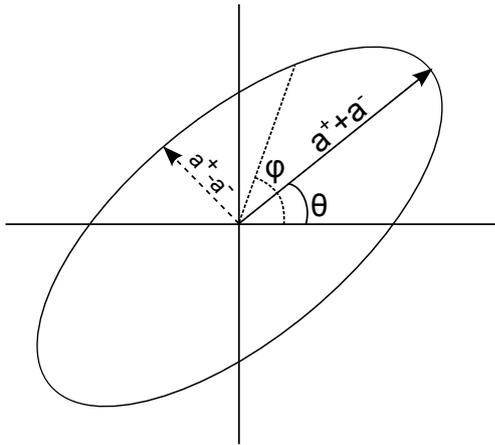


Figure 4. Tidal ellipse diagram, showing the four ellipse parameters: semi-major axis ($a^+ + a^-$), semi-minor axis ($a^+ - a^-$), inclination (θ), and Greenwich phase lag (φ).

of our discussion, the semi-major axis always aligns closely with the mean flow and the length of the semi-minor axis is small in all cases. The M_2 constituent, on the other hand, has a much larger semi-minor axis on the main body of the ice shelf arising from the rotational character of the semidiurnal tide in this region, as described by Makinson et al. (2012).

3 Results

Fortnightly variations in ice flow are observed across the entire FRIS region and its adjoining ice streams (Fig. 5a). As in the case of the RIS, the signal penetrates far upstream of the GLs of all ice streams that were monitored with the exception of Carlson Inlet, which is stagnant (King, 2011). At the most upstream sites of RIS (145 km upstream) and EIS (132 km upstream) there is some indication of an M_{sf} signal but errors are too large to say this with any certainty (Fig. 5a). The M_{sf} signal is largest at the ice shelf calving front, and generally larger in faster flowing regions.

A long-period modulation in horizontal ice flow at the S_{sa} frequency is also observed across much of the FRIS (Fig. 5b). The S_{sa} response, first observed on RIS by Murray et al. (2007), could only be determined at a few sites where the record covered a sufficiently long time period. The exact required record length will depend on noise in the GPS data but in practice it must be at least as long as the period of the S_{sa} constituent (~ 182 days). Where detectable, it shows similar characteristics to the M_{sf} signal, persisting upstream of GLs and with amplification towards the ice shelf calving front.

Amplitude of ice-shelf motion at the semidiurnal M_2 frequency is shown in Fig. 5c. As with the longer period signals, and as previously reported by Makinson et al. (2012), this semidiurnal component of horizontal ice motion is largest at the ice shelf calving front. Downstream of the RIS GL the low amplitude of M_2 is anomalous: all other ice streams

show a larger M_2 component in this portion of the ice shelf (Fig. 6).

Vertical diurnal tides are small compared with semidiurnal tides across the whole region (Fig. 1b) and this is reflected in the horizontal amplitude of the K_1 constituent, which is small throughout the domain (Fig. 5d). Qualitatively, its distribution is very similar to that of the M_2 signal; being strongest at the calving front and near ice stream grounding lines.

To demonstrate the dominance of the M_{sf} signal in the horizontal motion we show the predicted detrended displacements approximately 20 km upstream from the GL for each ice stream (Fig. 7). Also plotted is the vertical ocean tide (black line) on the ice shelf downstream of FIS. This site is chosen because, since the principle semidiurnal tides rotate in a clockwise direction around the FRIS, the vertical spring–neap cycle (and hence horizontal M_{sf} signal) will lead in phase at this point in our study region. Since GPS measurements were made over a number of years at different times the plot shows tidal prediction using UTide analysis of the sites, rather than actual data. Both RIS and EIS show the strongest M_{sf} signal upstream of the GL, but in all cases flow modulation at the M_{sf} frequency dominates at these timescales.

In order to assess more clearly how the tidal signal propagates upstream of the major ice stream GLs, we plot along-flow transects of tidal parameters for FIS, RIS, TIS, and EIS in Fig. 6. Error bars are the 95 % confidence intervals as calculated by UTide and described in the data analysis section. M_{sf} flow modulation persists far upstream of RIS, FIS, and EIS but is almost undetectable ~ 40 km upstream of TIS GL. M_{sf} phase shows lag both upstream of GLs and east to west along the coastline. The semidiurnal M_2 constituent decays very rapidly upstream of the GLs, in agreement with previous observations, and is stronger on the ice shelf in all cases apart from the RIS. M_2 phase is not shown as values upstream of the GL at almost all sites are subject to very high uncertainties as a result of the very low M_2 amplitude.

4 Discussion

The pervasive nature of the M_{sf} signal in horizontal ice flow across the entire region clearly shows that this nonlinear effect, first observed on the RIS, is the norm rather than an oddity only generated under very particular conditions. The implication is that learning how to reproduce these effects in models will teach us much about general ice rheology and flow in Antarctica.

Recent analysis of high-resolution SAR satellite data on the RIS has suggested that the M_{sf} signal is larger on the floating portion of the ice stream than on the grounded ice (Minchew et al., 2016). The compilation of GPS data that we present here shows that this amplification on floating ice generally continues all the way to the ice shelf front (Fig. 5). While these observations do not invalidate nonlinear mecha-

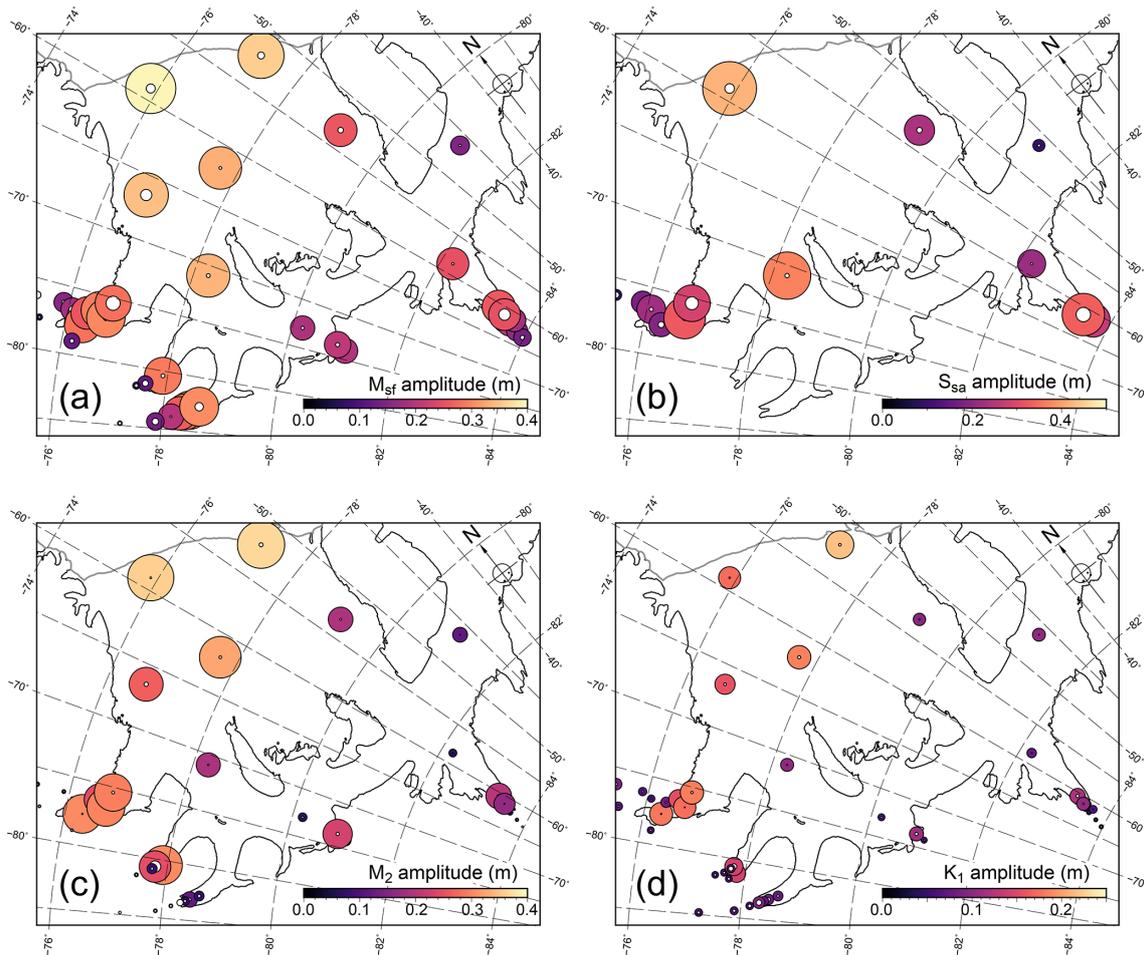


Figure 5. Tidal analysis of horizontal GPS displacements. Symbol area and colour show the semi-major axis amplitude. Error estimates for each component are overlain in white using the same scale. (Note that at most sites the errors are small compared to the amplitude and hence difficult to see.) Grounding lines are marked by black lines and the ice shelf front in grey.

nisms that generate the M_{sf} on grounded ice, they do suggest the need for a mechanism to generate fortnightly modulations in ice flow on floating ice. Minchew et al. (2016) proposed that widening of margins due to GL migration is one candidate that would produce an M_{sf} signal. While this may be the dominant mechanism in certain areas, such as the narrow embayment at the outlet of the RIS, it seems unlikely that this same mechanism is relevant over the entire FRIS where GL migration would only widen the ice shelf by a tiny fraction. Further modelling work is needed in order to explain the strength and spatial extent of the M_{sf} signal over the FRIS.

To better show the importance of the M_{sf} signal across the region, we interpolated amplitudes as measured by GPS from each site to cover the entire ice shelf and fast-flowing ice streams. The interpolation was done in MATLAB using the “v4” technique, which is based on the radial basis function method. The resulting map of M_{sf} amplitudes (Fig. 8a) gives a general impression of how the M_{sf} signal increases towards the calving front and decays upstream of GLs. Note

that in some regions of the ice shelf the interpolations are very poorly constrained and so should only be used as an indication of the spatial pattern of the M_{sf} signal (Fig. 5a).

The M_{sf} signal modulates ice speed at a fortnightly period. We calculate the tidally varying ice velocity by taking the time derivative of the harmonic fit to the horizontal time series. In Fig. 8b we show the change in velocity due only to the M_{sf} flow modulation (which we call the M_{sf} velocity) as a percent of the mean ice speed. This reveals areas where estimates of ice velocity are most susceptible to aliasing issues arising from the M_{sf} signal. Although M_{sf} amplitude increases towards the ice front, the mean flow speed also increases and so the net result is a somewhat lower relative effect on mean flow. The largest percentages are seen where major ice streams un-ground and flow into the ice shelf, with the ice flow modulation of $\pm 15\%$ over one fortnightly cycle.

In the same way that an interaction between the two principal semidiurnal constituents (M_2 and S_2) leads to an M_{sf} signal in ice flow, the two principal diurnal constituents (K_1

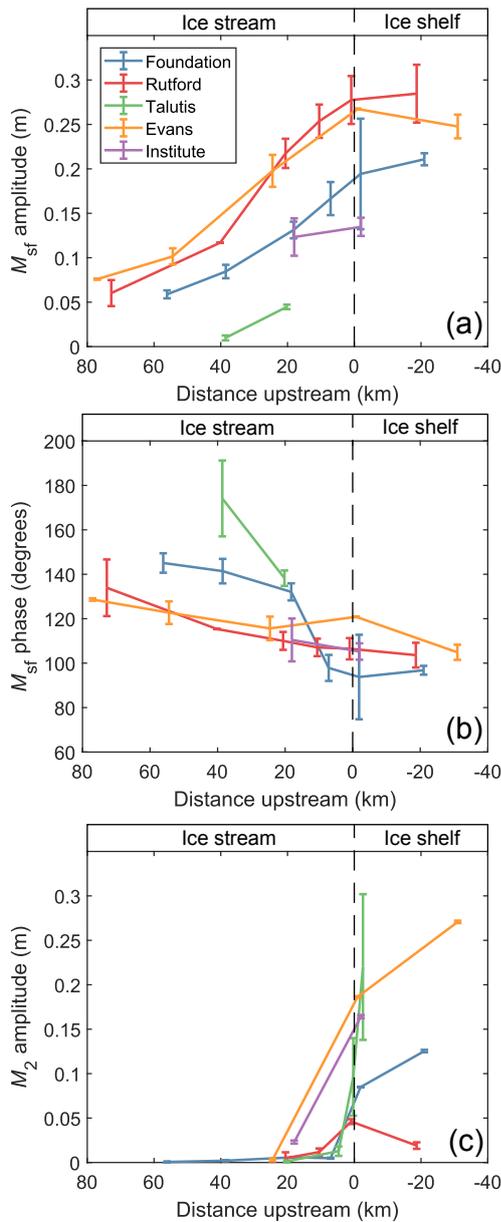


Figure 6. Along-flow transects across grounding lines of Foundation (blue lines), Rutford (red lines), Talutis (green lines), Evans (orange lines), and Institute (purple lines) ice streams showing M_{sf} amplitude (a), M_{sf} phase (b), and M_2 amplitude (c) calculated from tidal analysis of horizontal ice displacements measured by GPS. Transects consist of sites H08, H11, H01, H10 on FIS; R-20, R+00, R+10, R+20, R+40, R+73 on RIS; T-05, T-02, TT1, T+18, T+38 on TIS; E5, E4A, E3, E2A, E1 on EIS and IIS2, IIS1 on IIS. Error bars are the 95 % confidence intervals as calculated by UTide and described in the data analysis section. Note that transects do not follow exact flow lines.

and O_1) will interact nonlinearly to produce an M_f response. This is somewhat difficult to separate from the M_{sf} signal because they have a similar periodicity (Table 1). Given that the semidiurnal constituents are generally much larger than the

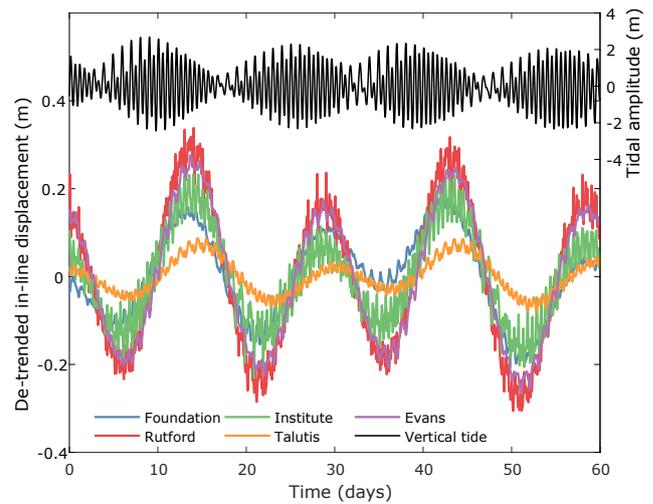


Figure 7. Horizontal de-trended displacements predicted for Foundation, Rutford, Talutis, and Evans ice streams based on GPS observations made approximately 20 km upstream in each case. Predicted vertical tidal motion on the freely floating outlet to FIS are also shown in black. Tidal reconstruction made using UTide software, including all tidal constituents with signal-to-noise ratio (SNR) > 2.

diurnals beneath the FRIS we can be confident that the M_{sf} response is most important, but there is likely to be some response in ice flow at the M_f frequency (King et al., 2010). Indeed, at the GL of the Ross Ice Shelf where the principal diurnal constituents are much larger than the semidiurnals, a response at the M_f frequency is readily observed (Marsh et al., 2013).

A further effect of the nonlinearity that generates a fortnightly modulation in ice flow is that it can increase the mean ice speed (Gudmundsson, 2007, 2011; Rosier et al., 2014b). A nonlinear mechanism is needed to generate the M_{sf} signal, i.e. horizontal ice flow (u) must have some nonlinear relationship to vertical ice-shelf displacements (h). This can be expressed most simply as $u \propto h^\alpha$ where $\alpha \neq 1$. Regardless of the mechanism being invoked, if $\alpha > 1$ the mean velocity will be increased, whereas a mechanism in which $\alpha < 1$ would reduce the mean velocity. All current theories that explain the M_{sf} signal on either ice shelves or ice streams find that $\alpha > 1$. The large spatial extent of the M_{sf} signal presented here implies that the flow of entire ice shelf is flowing faster than it would without this effect (or if the amplitude of the generating semidiurnal tides were to be reduced). Conversely, increased tidal amplitudes potentially caused by ice shelf retreat (Rosier et al., 2014a) could lead to a speed-up. Determining the amount by which the mean speed is affected as a result of the nonlinearity requires further modelling.

The amplitude of the M_{sf} signal at all sites shows some correlation with mean flow velocity ($R^2 = 0.653$, Fig. A1). The contrast in M_{sf} signal between Carlson Inlet and neighbouring TIS suggests that any valid mechanism for the generation of fortnightly flow modulation requires ice to be fast

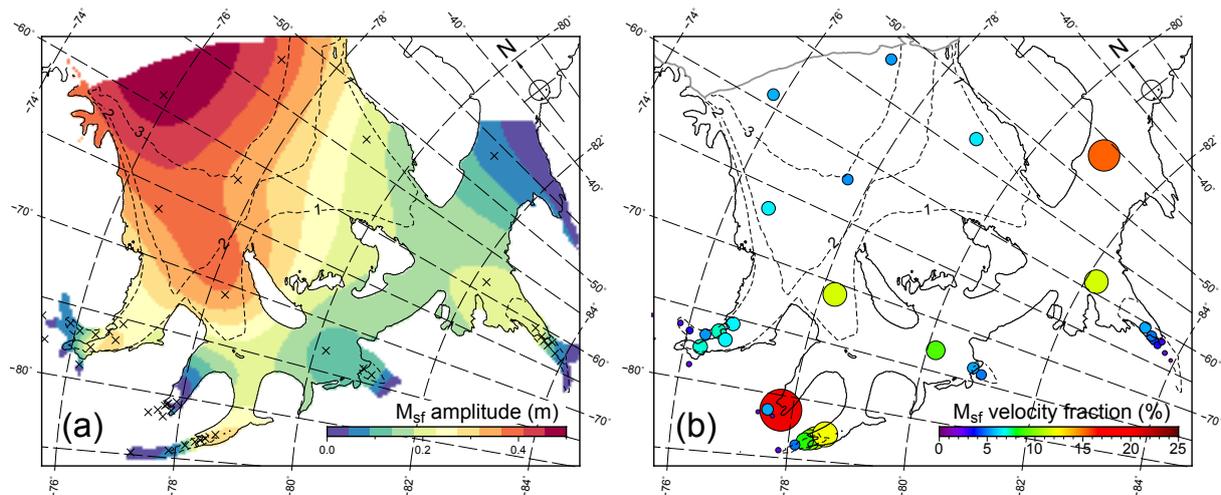


Figure 8. Interpolated amplitude of the M_{sf} signal (a) and M_{sf} velocity as a percentage of the mean speed (b, represented by symbol area and colour). The M_{sf} amplitude in (a) is interpolated from observations (black crosses, values shown in Fig. 5a) using MATLAB “v4” interpolation. Grounding lines are marked by black lines and dashed grey lines are ice velocity contours at 1 m d^{-1} intervals.

flowing, and that no measurable M_{sf} signal will be present upstream of slow-moving ice such as the stagnant Carlson Inlet. M_{sf} phase velocity upstream of ice stream GLs is somewhat uniform, with two notable exceptions. On FIS there is a long phase lag between 7 and 18 km upstream of the GL which might be linked to a large over-deepening in this portion of the ice stream (Joughin et al., 2006); more sites are needed to study this behaviour in detail.

All sites with sufficiently long records measured a clear S_{sa} tidal signal (Fig. 5b). The S_{sa} frequency is a long-period constituent that simulates the change in declination of the sun, which itself modulates the strength of the principal solar tidal constituent (S_2). As with the M_{sf} signal, there is almost no measurable vertical S_{sa} tide beneath the FRIS (Table 1). Long-period modulation in horizontal ice flow at the S_{sa} frequency has been observed previously on the RIS (Murray et al., 2007) and Larsen Ice Shelf (King et al., 2011a) and likely arises from the same nonlinear mechanism that generates the M_{sf} signal (King et al., 2010). Because of the long period of this signal, the apparently large amplitude has little effect on ice velocity from equinox to solstice. As a result it does not present the same aliasing dangers as the M_{sf} signal, which could affect satellite interferometric estimates of ice velocity (Gudmundsson, 2006).

5 Data availability

The new GPS data described herein are available through the UK Polar Data Centre in netCDF format (<https://doi.org/10.5285/4fe11286-0e53-4a03-854c-a79a44d1e356>) (H. Gudmundsson et al., 2017).

6 Conclusions

The extensive data set of GPS records and the large tidal ranges make the FRIS an excellent place to investigate tidal effects on ice flow. We have presented GPS observations from across the FRIS and adjoining ice streams, showing clear tidal modulation of horizontal ice flow at almost all sites upstream of the GL to ~ 80 km and downstream to the ice shelf front. This compilation of GPS data greatly expands on previous data sets, particularly for grounded ice. We also re-analysed previously released GPS results from the Filchner–Ronne Ice Shelf to search for longer period tidal effects that were not originally included.

Observations of these tidal effects are used extensively to gain insights into ice rheology and flow. Of particular interest is the fortnightly modulation in ice flow, not present in the tidal forcing but driven by a nonlinear response to the ocean tides. Previously, observations of this effect were limited to a few locations around Antarctica. This signal is easily observable at almost every site presented with a sufficiently long record to resolve it. In addition to short-term variations in flow, this nonlinear effect is likely to result in higher mean ice velocity. With the M_{sf} signal now demonstrated to cover the entire ice shelf system, in some cases with a larger amplitude than originally observed on RIS, there are clear implications for the flow of the entire FRIS.

Many aspects of these observations are still poorly understood and this new data set shows their relevance to general ice dynamics. In particular, no proposed mechanism can adequately explain the amplification of fortnightly variations in ice flow towards the ice front which is readily observable in this data set. Further theoretical and modelling work is needed to better understand the processes that lead to the flow of ice being so sensitive to ocean tides.

Appendix A: GPS stations

Table A1. Details of new GPS data presented in this study. New sites are in bold font. Total time is the time in days from first to last observation, whereas useful days is the number of days with at least 95 % of data.

Site name	Date first	Date last	Total (useful) days	Latitude (°)	Longitude (°)	Mean velocity (m d ⁻¹)	M_{sf} amplitude (m)	M_2 amplitude (m)
C+00	5-Dec-05	15-Dec-05	69 (24)	-77.85	-81.18	0.1	0.07	0.03
C+20	6-Dec-05	9-Feb-06	65 (65)	-77.72	-81.75	0.06	0	0
C-16	1-Feb-06	12-Feb-06	69 (17)	-77.92	-80.41	0.37	0.26	0.29
E1	26-Jan-09	12-Feb-09	284 (182)	-75.89	-76.27	1.19	0.08	0
E2A	19-Sep-09	6-Jan-10	345 (188)	-76.07	-76.63	1.27	0.1	0
E2B	26-Jan-09	7-May-09	347 (177)	-76.31	-77.58	1.52	0.25	0.29
E3	28-Jan-09	15-May-09	107 (106)	-76.35	-76.64	1.58	0.2	0
E4A	28-Jan-09	9-Mar-09	41 (41)	-76.56	-76.2	1.58	0.27	0.19
E4B	28-Jan-09	22-Apr-09	343 (170)	-76.7	-76.68	1.84	0.28	0.28
E5	9-Feb-09	18-Jul-09	339 (282)	-76.76	-75.41	1.57	0.25	0.27
EGPS	5-Dec-05	19-Jan-06	46 (46)	-76.19	-78.95	0.77	0.05	0
FR02	17-Dec-07	12-Apr-08	378 (212)	-80.99	-46.29	0.19	0.07	0.04
FR03	29-Jan-08	6-Apr-08	223 (76)	-82.21	-58.55	0.72	0.2	0.01
FR04	2-Dec-08	10-Jan-09	39 (39)	-80.18	-72.88	0.53	0.11	0.01
FR05	6-Dec-07	9-Dec-08	370 (344)	-78.26	-70.9	1.32	0.36	0.11
FR06	6-Dec-07	30-Jan-08	55 (55)	-76.69	-66.51	2.38	0.38	0.22
FR07	9-Dec-07	4-Jul-08	407 (320)	-75.88	-59.13	3.62	0.48	0.41
FR08	3-Dec-07	21-Dec-07	18 (18)	-77.68	-61.9	2.82	0.35	0.33
FR09	2-Dec-07	5-Oct-08	391 (358)	-79.15	-53.19	1.35	0.21	0.12
FR10	2-Dec-07	18-Feb-08	78 (78)	-77.19	-52.2	3.15	0.4	0.43
H01	28-Dec-15	27-Apr-16	362 (206)	-83.56	-61.58	1.67	0.16	0.01
H02	2-Jan-16	20-Mar-16	79 (79)	-83.65	-61.98	1.6	0.13	0.01
H04	2-Jan-16	5-Mar-16	64 (64)	-83.83	-62.55	1.52	0.08	0
H05	2-Jan-16	1-Mar-16	60 (60)	-83.97	-63.19	1.41	0.06	0
H08	10-Jan-16	17-Apr-16	97 (97)	-83.33	-60.55	1.61	0.21	0.13
H10	10-Jan-16	7-Apr-16	348 (165)	-83.69	-61.22	1.48	0.1	0
H11	1-Oct-16	23-Dec-16	361 (120)	-83.49	-61.19	1.69	0.19	0.09
IIS1	29-Jan-13	22-Jul-13	175 (175)	-81.04	-73.98	1.06	0.12	0.03
IIS2	18-Jan-14	20-May-14	123 (121)	-80.88	-73.54	1.03	0.13	0.16
R+00	22-Dec-03	15-Feb-04	56 (56)	-78.49	-83.09	1.08	0.28	0.05
R+10	22-Dec-03	13-Feb-04	54 (54)	-78.41	-83.28	1.09	0.25	0.01
R+20	21-Dec-03	13-Feb-04	54 (54)	-78.32	-83.47	1.1	0.21	0
R+40	18-Dec-03	25-Jan-04	39 (39)	-78.16	-83.85	1.02	0.12	0
R+73	5-Dec-05	13-Feb-06	71 (71)	-77.89	-84.41	0.99	0.06	0
R-20	23-Dec-03	15-Feb-04	55 (55)	-78.65	-82.67	0.99	0.29	0.02
R145	5-Dec-05	15-Feb-06	73 (73)	-77.25	-84.83	0.8	0	0
T+18	6-Dec-05	7-Feb-06	63 (63)	-77.62	-81.28	0.34	0.04	0
T+38	6-Dec-05	9-Feb-06	65 (65)	-77.47	-81.58	0.21	0.01	0
T-02	1-Feb-06	13-Feb-06	11 (11)	-77.76	-80.73	0.36	0	0.08
T-05	1-Feb-06	9-Feb-06	10 (10)	-77.78	-80.65	0.33	0	0.19
TT1	5-Feb-06	12-Feb-06	7 (7)	-77.73	-80.87	0.34	0	0.02
XX20	8-Jan-10	10-Apr-10	92 (92)	-75.53	-77.71	0.34	0.01	0
XX21	5-Feb-10	22-Apr-10	356 (177)	-75.4	-76.2	0.31	0.01	0

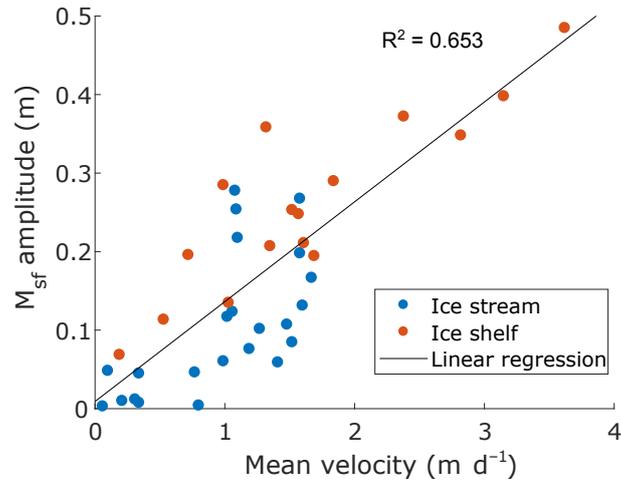


Figure A1. Relationship between mean velocity and M_{sf} amplitude for GPS sites on ice streams (blue circles) and ice shelves (red circles), along with a linear regression (black line) giving an R^2 value of 0.653. R^2 values for just ice streams or just ice shelves are 0.397 and 0.766, respectively. The few sites with no measurable M_{sf} amplitude are not included.

Competing interests. The authors declare that they have no conflict of interest.

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