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**A model of free-living gait; a factor analysis in Parkinson's disease**

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## **Abstract**

### Introduction

Gait is a marker of global health, cognition and falls risk. Gait is complex, comprised of multiple characteristics sensitive to survival, age and pathology. Due to covariance amongst characteristics, conceptual gait models have been established to reduce redundancy and aid interpretation. Previous models have been derived from laboratory gait assessments which are costly in equipment and time. Body-worn monitors (BWM) allow for free-living, low-cost and continuous gait measurement and produce similar covariant gait characteristics. A BWM gait model from both controlled and free-living measurement has not yet been established, limiting utility.

### Methods

103 control and 67 PD participants completed a controlled laboratory assessment; walking for two minutes around a circuit wearing a BWM. 89 control and 58 PD participants were assessed in free-living, completing normal activities for 7 days wearing a BWM. Fourteen gait characteristics were derived from the BWM, selected according to a previous model. Principle component analysis derived factor loadings of gait characteristics.

### Results

Four gait domains were derived for both groups and conditions; pace, rhythm, variability and asymmetry. Domains totalled 84.84% and 88.43% of variance for

controlled and 90.00% and 93.03% of variance in free-living environments for control and PD participants respectively. Gait characteristic loading was unambiguous for all characteristics apart from gait variability which demonstrated cross-loading for both groups and environments. The model was highly congruent with the original model.

### Conclusions

The conceptual gait models remained stable using a BWM in controlled and free-living environments. The model became more discrete supporting utility of the gait model for free-living gait.

**Keywords:** gait, free-living, Parkinson's disease, principle component analysis

## 1. Introduction

Gait is a marker of global health, cognition and falls risk [1, 2]. Gait is complex and multifactorial and whilst gait speed is widely used to reflect global performance and is sensitive to pathology and ageing it is not specific. Gait is comprised of multiple characteristics which if measured discretely can further discriminate gait alterations in response to neuropathological changes and ageing. Thus, measurement of gait characteristics over and above gait speed is critical in order to discern pathology and specific features of disease [3]. However, covariance amongst gait characteristics is high and in a bid to eliminate redundancy and ease interpretation, conceptual gait models have been developed [4-7]. Our earlier model identified five domains comprising 16 gait characteristics derived from GaitRite™ [4] (**Figure 1A**). Subsequently the model has been used to demonstrate associations of gait with age, gender and cognition [4, 8].

Traditionally, gait assessments have been undertaken in the laboratory which is costly in equipment and time. Accelerometer-based body worn monitors (BWM) provide a portable and affordable solution for assessment of discrete gait characteristics. BWM allow for prolonged data capture which is essential for fluctuating pathologies such as Parkinson's disease (PD). In addition, data can be collected in habitual environments reducing the influence of Hawthorne effect [9].

To date neither laboratory nor free-living gait characteristics derived from BWM have been applied to a conceptual framework, limiting their utility. Differences occur in gait metrics when comparing GaitRite™ with BWM as the latter measures continuous motion and the former discrete events (separate foot-falls). As a result, BWM

demonstrate increased sensitivity to asymmetry and variability characteristics [10]. In addition, BWM derive 14 of 16 characteristics due to limitations measuring step width and step width variability with single tri-axial accelerometers [10]. Thus, we hypothesise that free-living characteristics will load differently onto a conceptual gait model. Our aims were to i) explore a gait model using BWM in controlled and free-living environments in older adults and PD and ii) compare to our previous GaitRite™ derived model.

## **2. Methods**

### *2.1 Participants*

Subjects with newly diagnosed idiopathic PD were recruited from ICICLE-Gait, a nested study within ICICLE-PD (Incidence of cognitive impairment in cohorts of longitudinal evaluation-PD) between June 2009 and December 2011. Idiopathic PD was diagnosed according to UK PD brain bank criteria. Exclusion criteria included; memory impairment ( $\leq 24$  Mini Mental State Examination [MMSE]), dementia with Lewy bodies, Parkinson's plus syndromes, poor English and inability to consent. PD participants were tested three years post diagnosis. Age matched controls were recruited from community sources that were  $>60$  years, walked independently and had no significant cognitive impairment, mood or movement disorder. Full details of the recruitment process can be found in [11]. The study was approved by Newcastle and North Tyneside research and ethics committee.

### *2.2 Clinical Assessment*

Age, sex and body mass index (BMI) were recorded for all participants. Disease severity was measured using the Unified Parkinson's disease rating scale (UPDRS).

PD participants were assessed 'on' medication for controlled conditions, defined as within 1 hour of medication intake.

### *2.3 Gait Assessment*

Participants were asked to wear a single BWM (AX3; Axivity, York, UK; 100Hz,  $\pm 8g$ ) located at the fifth lumbar vertebra. During controlled assessment, participants walked for two minutes around a 25m circuit at preferred pace in a laboratory (see **Supplementary Figure 1**). The BWM was attached with a hydrogel adhesive (PALStickies, PAL Technologies, Glasgow, UK) and Hypafix (BSN Medical Limited, Hull, UK). For free-living assessment, participants wore the BWM continuously for 7 days [12].

### *2.4 Data Processing*

Recorded signals were stored locally on the sensor's internal memory and downloaded on assessment completion. Raw acceleration data for controlled and free-living assessments were analysed using a bespoke MATLAB<sup>®</sup> (Version 2015a) program, see [10] and [13] for further details of controlled and free-living data processing respectively. 14 previously validated spatiotemporal gait characteristics [10] were quantified (**Figure 1**).

### *2.5 Statistical analysis*

Free-living data were screened so full 7 day data were included in the analysis only. Data were inspected for outliers with histograms and boxplots. Student t-tests and Chi-squared tests were used to compare demographic data. Principle component analysis (PCA) was conducted to identify independent gait domains in controlled and free-living environments. A varimax rotation was applied to derive orthogonal factor scores with the minimum eigenvalue for extraction set at 1. Items which met a

minimum loading of 0.6 were considered significant. Loading value was increased from previous work due fewer participants [5, 14].

### **3. Results**

#### *3.1 Participants*

PD and control participants were matched for age ( $69.8 \pm 9.7$ , and  $72.3 \pm 6.7$  years respectively,  $p=.07$ ) and BMI ( $27.2 \pm 5.1$  and  $27.2 \pm 5.6$ ,  $p=1.00$  respectively). The PD group had significantly fewer females than controls (46M & 21F, versus 49M & 54F,  $p<.01$ ). PD participants presented with a mean (SD) UPDRS score of  $37.2 \pm 12.0$ .

#### *3.2 Controlled conditions*

103 control and 67 PD participants completed laboratory based assessment. The mean total number of steps performed by PD and control participants was  $226 \pm 22$  and  $237 \pm 23$  respectively.

Fourteen gait characteristics were entered into the PCA yielding four factors (pace, variability, rhythm and asymmetry) and accounted for 84.84% and 88.43% of variance for control and PD participants respectively. All item loadings were  $>0.6$  except for step length asymmetry in both groups with cross-loading evident for variability in controls (**Table 1, Figure 1B**).

#### *3.3 Free-living conditions*

Ninety-nine controls and 64 PD participants completed free-living assessment. Ten controls and six PD participants did not wear the BWM for the amount of time specified and were removed from analysis. Thus, a total of 89 controls and 58 PD participants were included.



The mean total number of steps per day completed by PD and control participants were  $11899 \pm 5183$  and  $13434 \pm 4393$  respectively. Fourteen gait characteristics were entered into the PCA yielding four factors in both groups (pace, variability, rhythm and asymmetry) and accounted for 90.00% and 93.03% of total variance for control and PD, respectively. All item loadings were  $>0.6$  with cross-loading evident for variability in both groups (**Table 2, Figure 1C**).

#### **4. Discussion**

This is the first study to our knowledge to explore conceptual gait models with BWM from controlled and free-living gait characteristics. Furthermore, the models remained stable compared to our previously published model derived from GaitRite™ data [4].

When creating our model, four discrete gait domains were identified under both conditions; showing that the domains are not protocol dependent. Unexpectedly, step length asymmetry loaded onto pace for controls. Previously, gait domains appear more discrete in pathological cohorts than healthy older adults [5]; this complements our findings and demonstrates the impact of PD on gait. Interestingly, step length asymmetry loaded onto the asymmetry domain in free-living for both groups. BWM are more sensitive at detecting characteristics of asymmetry [10] but in addition, perhaps due to environment complexity, asymmetry increased in free-living [13] thereby emphasising it.

We were unable to replicate the postural control domain, which in the earlier model was expressed by three gait characteristics (step width, step width variability and step length asymmetry). The first two cannot be measured using our BWM, and their

omission altered the factor loading for step length asymmetry. This is a limitation as postural control is a critical aspect of gait. Future algorithm development is underway for measurement of these characteristics with BWM. However, BWM's do provide a nuanced approach to postural control measurement [15] which could be used in addition to our gait model for simplistic clinical interpretation.

Although loading of variability characteristics demonstrated instability compared to other domains, in contrast to our previous model, characteristics loaded to one domain. Reasons may be twofold: similarly to asymmetry, BWM analysis appears to be more sensitive to variability characteristics compared to GaitRite [10] and; measures of variability become more accurate with increased step count [16].

This work shows stability of our gait model when using BWM derived characteristics. This is an important finding to inform future clinical research with progression of gait assessment into free-living.

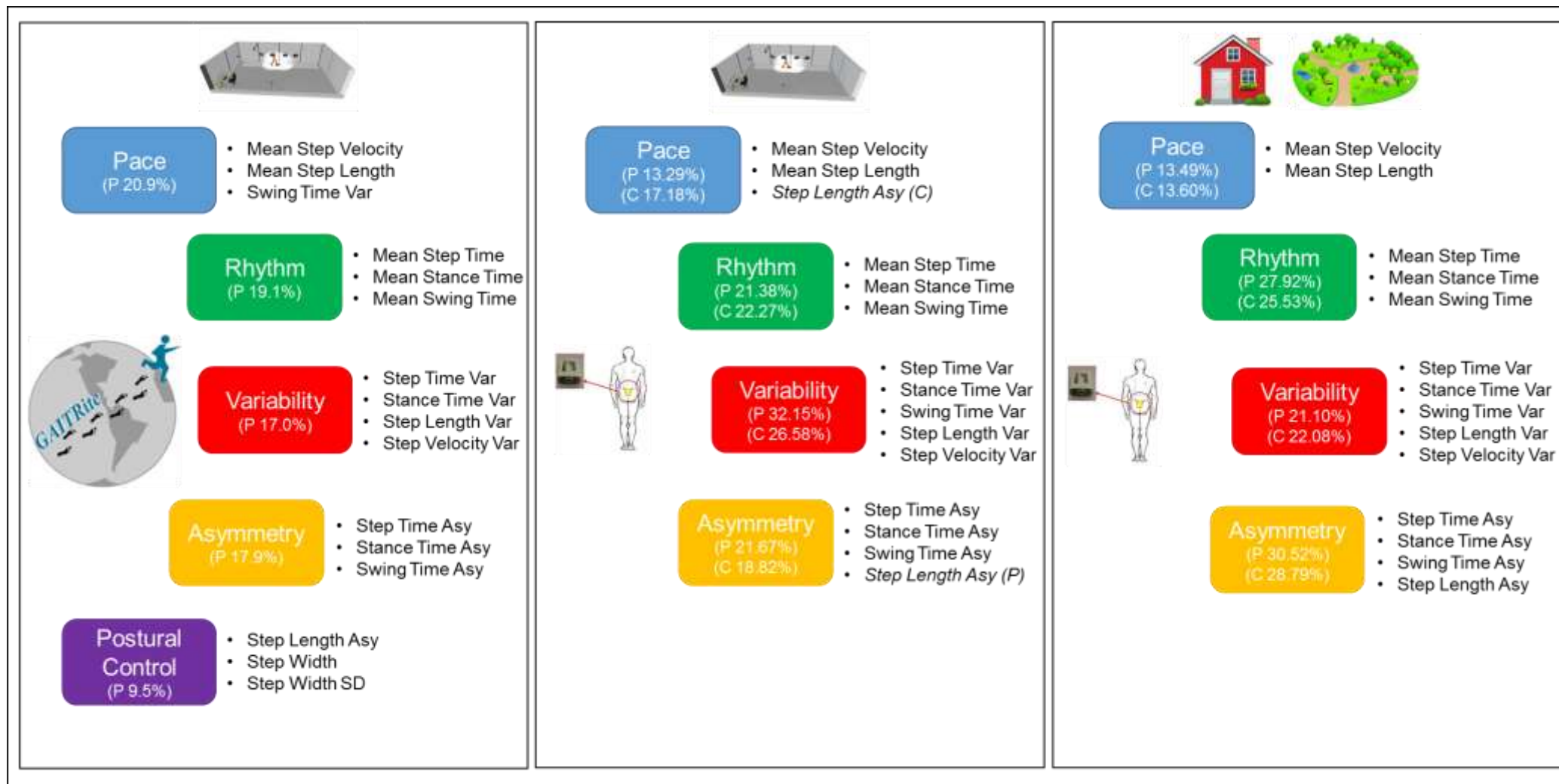
## **Conflicts of interest statement**

There are no conflicts of interest to report.

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**Figure 1.** Conceptual gait models derived **A)** previously using a pressure-sensor walkway in the laboratory **B)** with BWM in controlled conditions and **C)** with BWM in the free-living environment. (C)= control only, (P)= PD only.



**Table 1.** Item loadings of the principle component analysis for controlled (laboratory) BWM gait (Varimax rotation)

	PD (n=67)				Control (n=103)			
	Pace	Rhythm	Asymmetry	Variability	Pace	Rhythm	Asymmetry	Variability
<b>Pace</b>					<b>Pace</b>			
Step Velocity	<b>0.974</b>	0.108	-0.132	0.131	Step Velocity	<b>0.936</b>	0.201	-0.100
Step Length	<b>0.888</b>	-0.415	-0.143	0.010	Step Length	<b>0.845</b>	-0.422	-0.143
					<i>Step Length Asy</i>	<i>0.578</i>	<i>-0.203</i>	<i>0.231</i>
								<i>0.171</i>
<b>Rhythm</b>					<b>Rhythm</b>			
Step Time	-0.065	<b>0.951</b>	0.052	0.285	Step Time	-0.100	<b>0.970</b>	0.115
Stance Time	-0.067	<b>0.880</b>	0.152	0.192	Stance Time	-0.039	<b>0.938</b>	0.133
Swing Time	-0.050	<b>0.855</b>	-0.055	0.332	Swing Time	-0.161	<b>0.856</b>	0.074
								0.245
<b>Asymmetry</b>					<b>Asymmetry</b>			
Step Time Asy	-0.035	-0.048	<b>0.927</b>	0.104	Step Time Asy	0.126	0.118	<b>0.808</b>
Stance Time Asy	-0.112	0.074	<b>0.968</b>	0.089	Stance Time Asy	-0.076	0.089	<b>0.956</b>
Swing Time Asy	-0.093	0.098	<b>0.961</b>	0.099	Swing Time Asy	-0.056	0.085	<b>0.965</b>
<i>Step length Asy</i>	<i>-0.184</i>	<i>0.352</i>	<i>0.405</i>	<i>0.251</i>				0.070
<b>Variability (SD)</b>					<b>Variability (SD)</b>			
Step Time Var	-0.027	0.222	0.196	<b>0.922</b>	Step Time Var	-0.038	0.228	-0.024
Stance Time Var	-0.048	0.269	0.129	<b>0.922</b>	Stance Time Var	-0.074	0.244	0.025
Swing Time Var	-0.065	0.275	0.126	<b>0.920</b>	Swing Time Var	-0.163	0.281	0.039
Step Length Var	0.133	0.227	0.058	<b>0.889</b>	Step Length Var	0.400	-0.079	0.079
Step Velocity Var	0.177	0.098	0.042	<b>0.909</b>	Step Velocity Var	0.473	-0.280	0.080
								<b>0.679</b>
<b>% Variance (88.43%)</b>	13.29%	21.38%	21.67%	32.15%	<b>% Variance (84.84%)</b>	17.18%	22.27%	18.82%
								26.58%

**Table 2.** Item loadings of the principle component analysis for free-living BWM gait (Varimax rotation).

	PD (n=58)				Control (n=89)			
	Pace	Rhythm	Asymmetry	Variability	Pace	Rhythm	Asymmetry	Variability
<b>Pace</b>					<b>Pace</b>			
Step Velocity	<b>0.991</b>	-0.024	-0.016	0.014	Step Velocity	<b>0.797</b>	-0.054	-0.109
Step Length	<b>0.789</b>	-0.562	0.122	0.140	Step Length	<b>0.970</b>	-0.558	0.119
<b>Rhythm</b>					<b>Rhythm</b>			
Step Time	-0.088	<b>0.974</b>	0.160	0.114	Step Time	-0.110	<b>0.982</b>	0.072
Stance Time	-0.067	<b>0.927</b>	0.248	0.166	Stance Time	-0.065	<b>0.950</b>	0.166
Swing Time	-0.131	<b>0.945</b>	0.014	0.079	Swing Time	-0.191	<b>0.936</b>	-0.033
<b>Asymmetry</b>					<b>Asymmetry</b>			
Step Time Asy	-0.002	0.130	<b>0.959</b>	0.209	Step Time Asy	-0.104	0.085	<b>0.968</b>
Stance Time Asy	-0.029	0.130	<b>0.967</b>	0.140	Stance Time Asy	-0.082	0.043	<b>0.968</b>
Swing Time Asy	-0.060	0.101	<b>0.950</b>	0.119	Swing Time Asy	-0.082	0.096	<b>0.915</b>
Step Length Asy	0.274	0.058	<b>0.780</b>	0.240	Step Length Asy	0.227	-0.053	<b>0.728</b>
<b>Variability (SD)</b>					<b>Variability (SD)</b>			
Step Time	-0.165	0.463	0.522	<b>0.664</b>	Step Time	-0.251	0.358	0.493
Stance Time	-0.182	0.465	0.533	<b>0.624</b>	Stance Time	-0.241	0.280	0.525
Swing Time	-0.215	0.542	0.435	<b>0.660</b>	Swing Time	-0.229	0.448	0.451
Step Length	0.088	0.226	0.073	<b>0.856</b>	Step Length	-0.100	0.228	-0.070
Step Velocity	0.242	-0.261	0.231	<b>0.869</b>	Step Velocity	0.123	-0.193	0.033
<b>% Variance (93.03%)</b>	13.49%	27.92%	30.52%	21.10%	<b>% Variance (90.00%)</b>	13.60%	25.53%	28.79%

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